

Now, with
Navier-Stokes Eqn

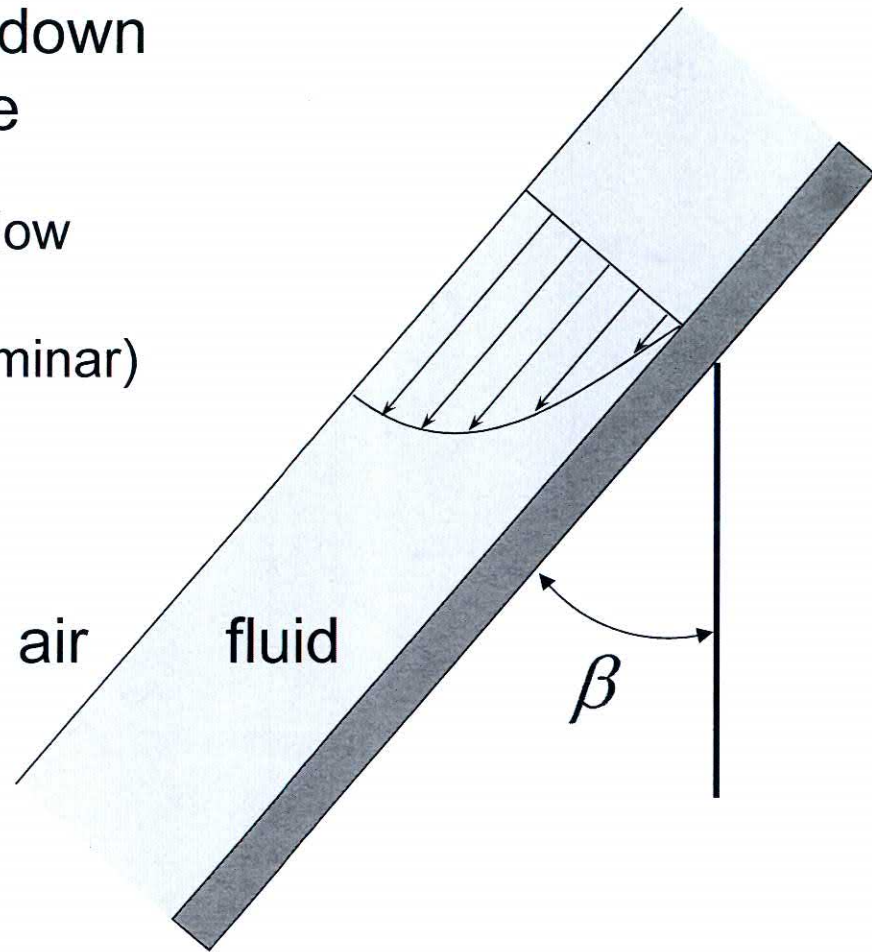
21 Sept 2015

0.5

EXAMPLE 1: Flow of a Newtonian fluid down an inclined plane

- fully developed flow
- steady state
- flow in layers (laminar)

\underline{g}



1

The Equation of Continuity and the Equation of Motion in Cartesian, cylindrical, and spherical coordinates

Steady CM3110 Fall 2011 Faith A. Morrison **constant ρ**

Continuity Equation, Cartesian coordinates

$$\frac{\partial \rho}{\partial t} + \left(v_x \frac{\partial \rho}{\partial x} + v_y \frac{\partial \rho}{\partial y} + v_z \frac{\partial \rho}{\partial z} \right) + \rho \left(\frac{\partial v_x}{\partial x} + \frac{\partial v_y}{\partial y} + \frac{\partial v_z}{\partial z} \right) = 0$$

Continuity Equation, cylindrical coordinates

$$\frac{\partial \rho}{\partial t} + \frac{1}{r} \frac{\partial(\rho r v_r)}{\partial r} + \frac{1}{r} \frac{\partial(\rho v_\theta)}{\partial \theta} + \frac{\partial(\rho v_z)}{\partial z} = 0$$

Continuity Equation, spherical coordinates

$$\frac{\partial \rho}{\partial t} + \frac{1}{r^2} \frac{\partial(\rho r^2 v_r)}{\partial r} + \frac{1}{r \sin \theta} \frac{\partial(\rho v_\theta \sin \theta)}{\partial \theta} + \frac{1}{r \sin \theta} \frac{\partial(\rho v_\phi)}{\partial \phi} = 0$$

$$\frac{\partial v_z}{\partial z} = 0$$

Equation of Motion for an incompressible fluid, 3 components in Cartesian coordinates

$\underline{v} = (0, 0, v_z)$

$$\begin{aligned} \rho \left(\frac{\partial v_x}{\partial t} + v_x \frac{\partial v_x}{\partial x} + v_y \frac{\partial v_x}{\partial y} + v_z \frac{\partial v_x}{\partial z} \right) &= -\frac{\partial P}{\partial x} + \left(\frac{\partial \tilde{\tau}_{xx}}{\partial x} + \frac{\partial \tilde{\tau}_{yx}}{\partial y} + \frac{\partial \tilde{\tau}_{zx}}{\partial z} \right) + \rho g_x \\ \rho \left(\frac{\partial v_y}{\partial t} + v_x \frac{\partial v_y}{\partial x} + v_y \frac{\partial v_y}{\partial y} + v_z \frac{\partial v_y}{\partial z} \right) &= -\frac{\partial P}{\partial y} + \left(\frac{\partial \tilde{\tau}_{xy}}{\partial x} + \frac{\partial \tilde{\tau}_{yy}}{\partial y} + \frac{\partial \tilde{\tau}_{zy}}{\partial z} \right) + \rho g_y \\ \rho \left(\frac{\partial v_z}{\partial t} + v_x \frac{\partial v_z}{\partial x} + v_y \frac{\partial v_z}{\partial y} + v_z \frac{\partial v_z}{\partial z} \right) &= -\frac{\partial P}{\partial z} + \left(\frac{\partial \tilde{\tau}_{xz}}{\partial x} + \frac{\partial \tilde{\tau}_{yz}}{\partial y} + \frac{\partial \tilde{\tau}_{zz}}{\partial z} \right) + \rho g_z \end{aligned}$$

Equation of Motion for an incompressible fluid, 3 components in cylindrical coordinates

$$\begin{aligned} \rho \left(\frac{\partial v_r}{\partial t} + v_r \frac{\partial v_r}{\partial r} + \frac{v_\theta}{r} \frac{\partial v_r}{\partial \theta} - \frac{v_\theta^2}{r} + v_z \frac{\partial v_r}{\partial z} \right) &= -\frac{\partial P}{\partial r} + \left(\frac{1}{r} \frac{\partial(r \tilde{\tau}_{rr})}{\partial r} + \frac{1}{r} \frac{\partial \tilde{\tau}_{\theta r}}{\partial \theta} - \frac{\tilde{\tau}_{\theta\theta}}{r} + \frac{\partial \tilde{\tau}_{zr}}{\partial z} \right) + \rho g_r \\ \rho \left(\frac{\partial v_\theta}{\partial t} + v_r \frac{\partial v_\theta}{\partial r} + \frac{v_\theta}{r} \frac{\partial v_\theta}{\partial \theta} + \frac{v_\theta v_r}{r} + v_z \frac{\partial v_\theta}{\partial z} \right) &= -\frac{1}{r} \frac{\partial P}{\partial \theta} + \left(\frac{1}{r^2} \frac{\partial(r^2 \tilde{\tau}_{r\theta})}{\partial r} + \frac{1}{r} \frac{\partial \tilde{\tau}_{\theta\theta}}{\partial \theta} + \frac{\partial \tilde{\tau}_{z\theta}}{\partial z} + \frac{\tilde{\tau}_{\theta r} - \tilde{\tau}_{r\theta}}{r} \right) + \rho g_\theta \\ \rho \left(\frac{\partial v_z}{\partial t} + v_r \frac{\partial v_z}{\partial r} + \frac{v_\theta}{r} \frac{\partial v_z}{\partial \theta} + v_z \frac{\partial v_z}{\partial z} \right) &= -\frac{\partial P}{\partial z} + \left(\frac{1}{r} \frac{\partial(r \tilde{\tau}_{rz})}{\partial r} + \frac{1}{r} \frac{\partial \tilde{\tau}_{\theta z}}{\partial \theta} + \frac{\partial \tilde{\tau}_{zz}}{\partial z} \right) + \rho g_z \end{aligned}$$

Equation of Motion for an incompressible fluid, 3 components in spherical coordinates

$$\begin{aligned} &\rho \left(\frac{\partial v_r}{\partial t} + v_r \frac{\partial v_r}{\partial r} + \frac{v_\theta}{r} \frac{\partial v_r}{\partial \theta} + \frac{v_\phi}{r \sin \theta} \frac{\partial v_r}{\partial \phi} - \frac{v_\theta^2 + v_\phi^2}{r} \right) \\ &= -\frac{\partial P}{\partial r} + \left(\frac{1}{r^2} \frac{\partial(r^2 \tilde{\tau}_{rr})}{\partial r} + \frac{1}{r \sin \theta} \frac{\partial(\tilde{\tau}_{\theta r} \sin \theta)}{\partial \theta} + \frac{1}{r \sin \theta} \frac{\partial \tilde{\tau}_{\phi r}}{\partial \phi} - \frac{\tilde{\tau}_{\theta\theta} + \tilde{\tau}_{\phi\phi}}{r} \right) + \rho g_r \\ &\rho \left(\frac{\partial v_\theta}{\partial t} + v_r \frac{\partial v_\theta}{\partial r} + \frac{v_\theta}{r} \frac{\partial v_\theta}{\partial \theta} + \frac{v_\phi}{r \sin \theta} \frac{\partial v_\theta}{\partial \phi} + \frac{v_r v_\theta}{r} - \frac{v_\phi^2 \cot \theta}{r} \right) \\ &= -\frac{1}{r} \frac{\partial P}{\partial \theta} + \left(\frac{1}{r^3} \frac{\partial(r^3 \tilde{\tau}_{r\theta})}{\partial r} + \frac{1}{r \sin \theta} \frac{\partial(\tilde{\tau}_{\theta\theta} \sin \theta)}{\partial \theta} + \frac{1}{r \sin \theta} \frac{\partial \tilde{\tau}_{\phi\theta}}{\partial \phi} + \frac{\tilde{\tau}_{\theta r} - \tilde{\tau}_{r\theta}}{r} - \frac{\tilde{\tau}_{\phi\phi} \cot \theta}{r} \right) + \rho g_\theta \\ &\rho \left(\frac{\partial v_\phi}{\partial t} + v_r \frac{\partial v_\phi}{\partial r} + \frac{v_\theta}{r} \frac{\partial v_\phi}{\partial \theta} + \frac{v_\phi}{r \sin \theta} \frac{\partial v_\phi}{\partial \phi} + \frac{v_r v_\phi}{r} + \frac{v_\theta v_\phi \cot \theta}{r} \right) \\ &= -\frac{1}{r \sin \theta} \frac{\partial P}{\partial \phi} + \left(\frac{1}{r^3} \frac{\partial(r^3 \tilde{\tau}_{r\phi})}{\partial r} + \frac{1}{r \sin \theta} \frac{\partial(\tilde{\tau}_{\theta\phi} \sin \theta)}{\partial \theta} + \frac{1}{r \sin \theta} \frac{\partial \tilde{\tau}_{\phi\phi}}{\partial \phi} + \frac{\tilde{\tau}_{\phi r} - \tilde{\tau}_{r\phi}}{r} + \frac{\tilde{\tau}_{\theta\phi} \cot \theta}{r} \right) + \rho g_\phi \end{aligned}$$

The Equation of Continuity and the Equation of Motion in Cartesian, cylindrical, and spherical coordinates

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Continuity Equation, Cartesian coordinates

$$\frac{\partial \rho}{\partial t} + \left(v_x \frac{\partial \rho}{\partial x} + v_y \frac{\partial \rho}{\partial y} + v_z \frac{\partial \rho}{\partial z} \right) + \rho \left(\frac{\partial v_x}{\partial x} + \frac{\partial v_y}{\partial y} + \frac{\partial v_z}{\partial z} \right) = 0$$

→ Continuity Equation, cylindrical coordinates

$$\frac{\partial \rho}{\partial t} + \frac{1}{r} \frac{\partial(\rho r v_r)}{\partial r} + \frac{1}{r} \frac{\partial(\rho v_\theta)}{\partial \theta} + \frac{\partial(\rho v_z)}{\partial z} = 0$$

Continuity Equation, spherical coordinates

$$\rho = \text{constant} \quad \frac{\partial \rho}{\partial t} + \frac{1}{r^2} \frac{\partial(\rho r^2 v_r)}{\partial r} + \frac{1}{r \sin \theta} \frac{\partial(\rho v_\theta \sin \theta)}{\partial \theta} + \frac{1}{r \sin \theta} \frac{\partial(\rho v_\phi)}{\partial \phi} = 0$$

Equation of Motion for an incompressible fluid, 3 components in Cartesian coordinates

$$\begin{aligned} \rho \left(\frac{\partial v_x}{\partial t} + v_x \frac{\partial v_x}{\partial x} + v_y \frac{\partial v_x}{\partial y} + v_z \frac{\partial v_x}{\partial z} \right) &= -\frac{\partial P}{\partial x} + \left(\frac{\partial \tilde{\tau}_{xx}}{\partial x} + \frac{\partial \tilde{\tau}_{yx}}{\partial y} + \frac{\partial \tilde{\tau}_{zx}}{\partial z} \right) + \rho g_x \\ \rho \left(\frac{\partial v_y}{\partial t} + v_x \frac{\partial v_y}{\partial x} + v_y \frac{\partial v_y}{\partial y} + v_z \frac{\partial v_y}{\partial z} \right) &= -\frac{\partial P}{\partial y} + \left(\frac{\partial \tilde{\tau}_{xy}}{\partial x} + \frac{\partial \tilde{\tau}_{yy}}{\partial y} + \frac{\partial \tilde{\tau}_{zy}}{\partial z} \right) + \rho g_y \\ \rho \left(\frac{\partial v_z}{\partial t} + v_x \frac{\partial v_z}{\partial x} + v_y \frac{\partial v_z}{\partial y} + v_z \frac{\partial v_z}{\partial z} \right) &= -\frac{\partial P}{\partial z} + \left(\frac{\partial \tilde{\tau}_{xz}}{\partial x} + \frac{\partial \tilde{\tau}_{yz}}{\partial y} + \frac{\partial \tilde{\tau}_{zz}}{\partial z} \right) + \rho g_z \end{aligned}$$

Equation of Motion for an incompressible fluid, 3 components in cylindrical coordinates

$$\begin{aligned} \rho \left(\frac{\partial v_r}{\partial t} + v_r \frac{\partial v_r}{\partial r} + \frac{v_\theta}{r} \frac{\partial v_r}{\partial \theta} + \frac{v_\theta^2}{r} + v_z \frac{\partial v_r}{\partial z} \right) &= -\frac{\partial P}{\partial r} + \left(\frac{1}{r} \frac{\partial(r \tilde{\tau}_{rr})}{\partial r} - \frac{1}{r} \frac{\partial \tilde{\tau}_{\theta r}}{\partial \theta} - \frac{\tilde{\tau}_{\theta\theta}}{r} + \frac{\partial \tilde{\tau}_{zr}}{\partial z} \right) + \rho g_r \\ \rho \left(\frac{\partial v_\theta}{\partial t} + v_r \frac{\partial v_\theta}{\partial r} + \frac{v_\theta}{r} \frac{\partial v_\theta}{\partial \theta} + \frac{v_\theta v_r}{r} + v_z \frac{\partial v_\theta}{\partial z} \right) &= -\frac{1}{r} \frac{\partial P}{\partial \theta} + \left(\frac{1}{r^2} \frac{\partial(r^2 \tilde{\tau}_{r\theta})}{\partial r} + \frac{1}{r} \frac{\partial \tilde{\tau}_{\theta\theta}}{\partial \theta} + \frac{\partial \tilde{\tau}_{z\theta}}{\partial z} + \frac{\tilde{\tau}_{\theta r} - \tilde{\tau}_{r\theta}}{r} \right) + \rho g_\theta \\ \rho \left(\frac{\partial v_z}{\partial t} + v_r \frac{\partial v_z}{\partial r} + \frac{v_\theta}{r} \frac{\partial v_z}{\partial \theta} + v_z \frac{\partial v_z}{\partial z} \right) &= -\frac{\partial P}{\partial z} + \left(\frac{1}{r} \frac{\partial(r \tilde{\tau}_{rz})}{\partial r} + \frac{1}{r} \frac{\partial \tilde{\tau}_{\theta z}}{\partial \theta} + \frac{\partial \tilde{\tau}_{zz}}{\partial z} \right) + \rho g_z \end{aligned}$$

Equation of Motion for an incompressible fluid, 3 components in spherical coordinates

$$\begin{aligned} \rho \left(\frac{\partial v_r}{\partial t} + v_r \frac{\partial v_r}{\partial r} + \frac{v_\theta}{r} \frac{\partial v_r}{\partial \theta} + \frac{v_\phi}{r \sin \theta} \frac{\partial v_r}{\partial \phi} - \frac{v_\theta^2 + v_\phi^2}{r} \right) &= -\frac{\partial P}{\partial r} + \left(\frac{1}{r^2} \frac{\partial(r^2 \tilde{\tau}_{rr})}{\partial r} + \frac{1}{r \sin \theta} \frac{\partial(\tilde{\tau}_{\theta r} \sin \theta)}{\partial \theta} + \frac{1}{r \sin \theta} \frac{\partial \tilde{\tau}_{\phi r}}{\partial \phi} - \frac{\tilde{\tau}_{\theta\theta} + \tilde{\tau}_{\phi\phi}}{r} \right) + \rho g_r \\ \rho \left(\frac{\partial v_\theta}{\partial t} + v_r \frac{\partial v_\theta}{\partial r} + \frac{v_\theta}{r} \frac{\partial v_\theta}{\partial \theta} + \frac{v_\phi}{r \sin \theta} \frac{\partial v_\theta}{\partial \phi} + \frac{v_r v_\theta}{r} - \frac{v_\phi^2 \cot \theta}{r} \right) &= -\frac{1}{r} \frac{\partial P}{\partial \theta} + \left(\frac{1}{r^3} \frac{\partial(r^3 \tilde{\tau}_{r\theta})}{\partial r} + \frac{1}{r \sin \theta} \frac{\partial(\tilde{\tau}_{\theta\theta} \sin \theta)}{\partial \theta} + \frac{1}{r \sin \theta} \frac{\partial \tilde{\tau}_{\phi\theta}}{\partial \phi} + \frac{\tilde{\tau}_{\theta r} - \tilde{\tau}_{r\theta}}{r} - \frac{\tilde{\tau}_{\phi\phi} \cot \theta}{r} \right) + \rho g_\theta \\ \rho \left(\frac{\partial v_\phi}{\partial t} + v_r \frac{\partial v_\phi}{\partial r} + \frac{v_\theta}{r} \frac{\partial v_\phi}{\partial \theta} + \frac{v_\phi}{r \sin \theta} \frac{\partial v_\phi}{\partial \phi} + \frac{v_r v_\phi}{r} + \frac{v_\theta v_\phi \cot \theta}{r} \right) &= -\frac{1}{r \sin \theta} \frac{\partial P}{\partial \phi} + \left(\frac{1}{r^3} \frac{\partial(r^3 \tilde{\tau}_{r\phi})}{\partial r} + \frac{1}{r \sin \theta} \frac{\partial(\tilde{\tau}_{\theta\phi} \sin \theta)}{\partial \theta} + \frac{1}{r \sin \theta} \frac{\partial \tilde{\tau}_{\phi\phi}}{\partial \phi} + \frac{\tilde{\tau}_{\phi r} - \tilde{\tau}_{r\phi}}{r} + \frac{\tilde{\tau}_{\theta\phi} \cot \theta}{r} \right) + \rho g_\phi \end{aligned}$$

x-component of Navier Stokes (NS): ⁽³⁾
Eqn of Motion (EOM)

$$0 = -\frac{\partial P}{\partial x} + \rho g \sin \beta$$

$$\frac{\partial P}{\partial x} = \rho g \sin \beta$$

y-component of NS:

$$0 = -\frac{\partial P}{\partial y}$$



P does not depend on y

z-component of NS:

$$0 = -\frac{\partial P}{\partial z} + \mu \frac{\partial^2 v_z}{\partial x^2} + \rho g \cos \beta$$



does P vary in z-dir?

$$z=0 \quad P = P_{atm}$$

$$z=L \quad P = P_{atm}$$

$$z = \text{anything} \quad P = P_{atm}$$

} No variation

$$\Rightarrow \frac{\partial P}{\partial z} = 0 //$$

Now the eqn becomes:

$$0 = \mu \frac{\partial^2 v_z}{\partial x^2} + \rho g \cos \beta$$

$$\underline{v} = \begin{pmatrix} 0 \\ 0 \\ v_z \end{pmatrix}_{x, y, z} \quad v_z(x) \text{ only}$$

$$0 = \mu \frac{d^2 v_z}{dx^2} + \rho g \cos \beta$$

Solve:

$$\frac{d^2 v_z}{dx^2} = \frac{-\rho g \cos \beta}{\mu}$$

5

$$\frac{d}{dx} \left(\frac{dV_z}{dx} \right) = \left(\frac{-\rho g \cos \beta}{r} \right) = C$$

$$\frac{d\Phi}{dx} = C$$

use substitution
to make clear
what integration
is needed

$$\frac{dV_z}{dx} = \Phi = Cx + C_1$$

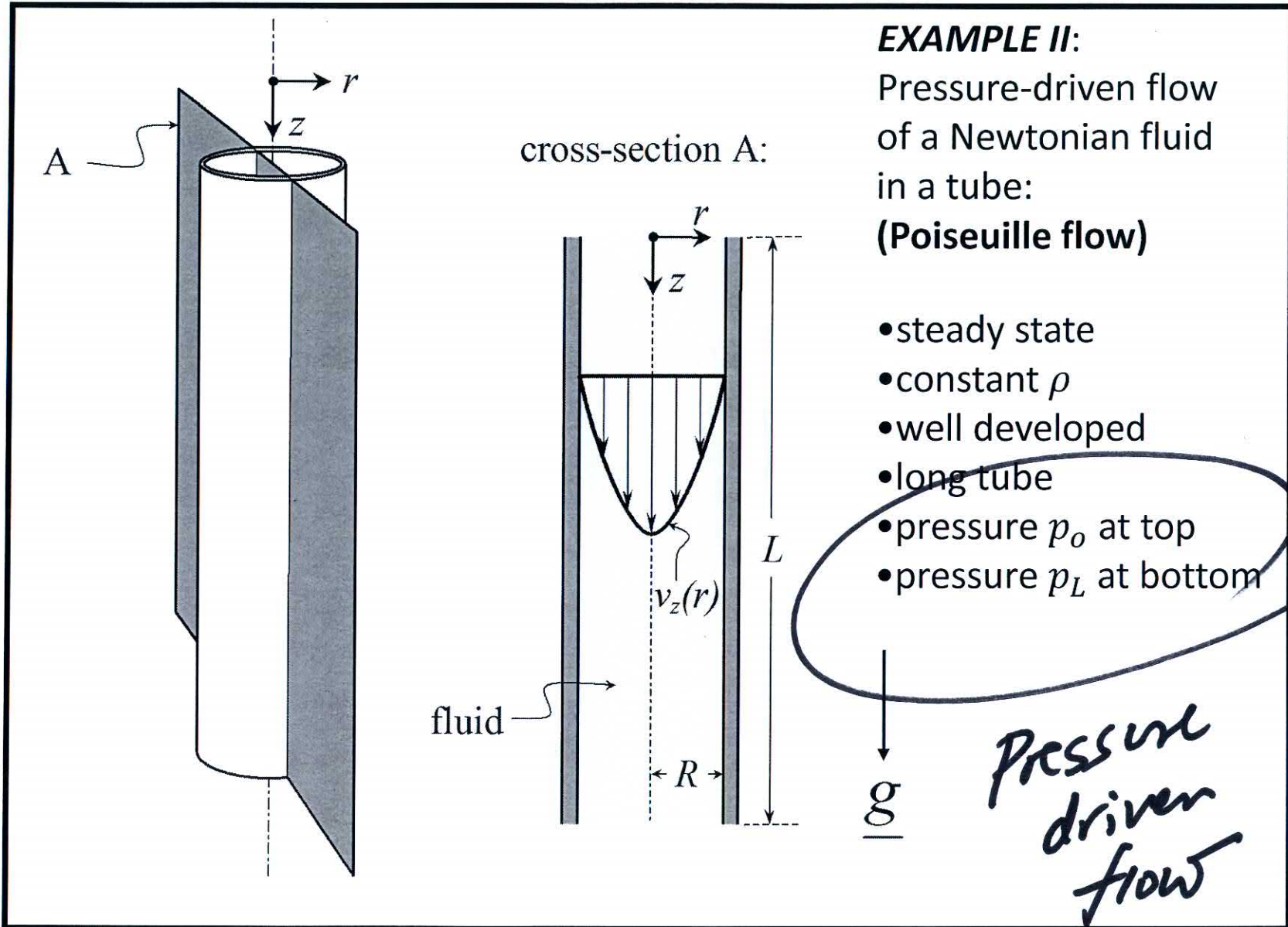
$$\frac{dV_z}{dx} = Cx + C_1$$

$$V_z = C \frac{x^2}{2} + C_1 x + C_2$$

—continue
as
before.

EXAMPLE 2:

0.25



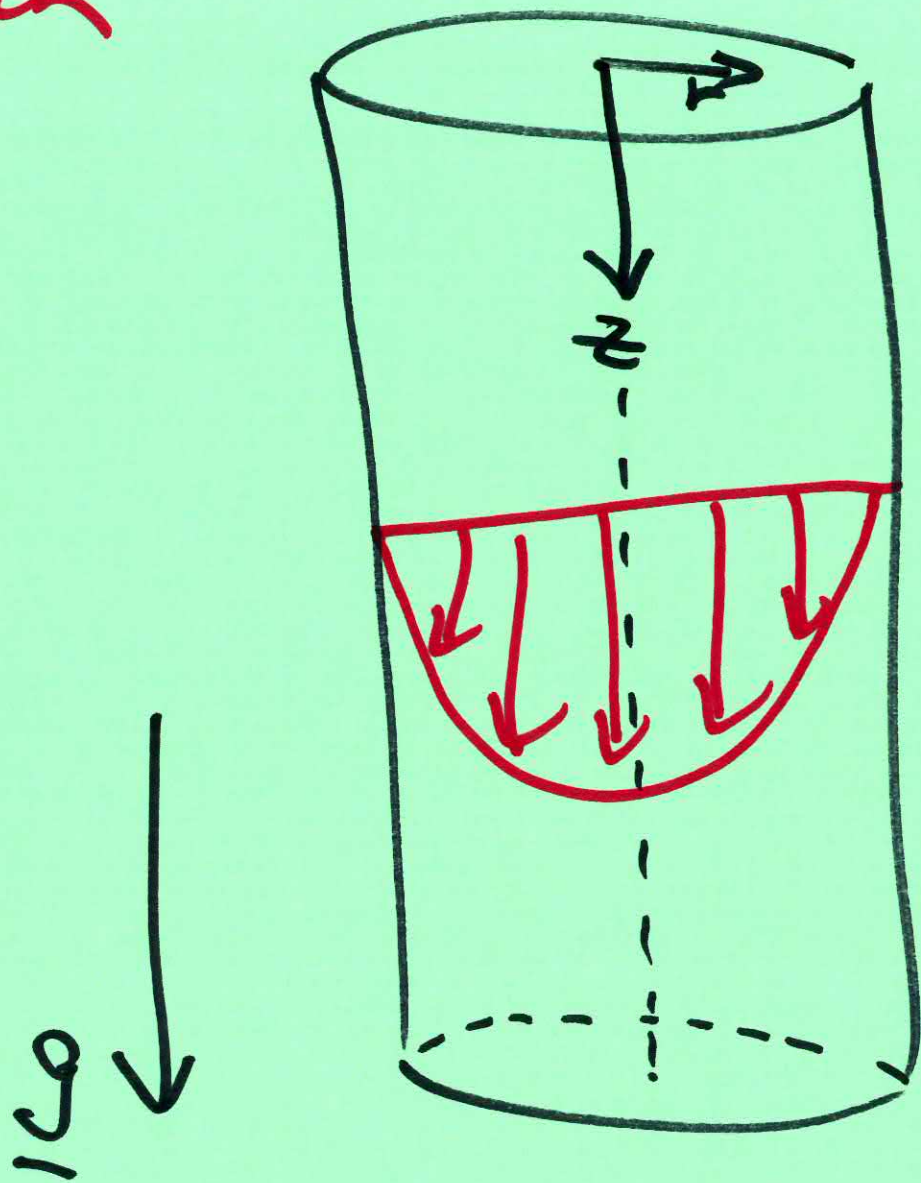
A harder problem: tube flow

0.50

Calculate the velocity field in a 10^{19} pipe of circular cross section of an incompressible Newtonian fluid at steady state. Pressure at top is P_0 and a distance L downstream the pressure is P_L .

21 Sept
2015

Sketch



model
the flow

①

$$\underline{v} = \begin{pmatrix} v_r \\ v_\theta \\ v_z \end{pmatrix}_{r\theta z}$$
$$= \begin{pmatrix} 0 \\ 0 \\ v_z \end{pmatrix}_{r\theta z}$$

Equation of Motion for incompressible, Newtonian fluid (Navier-Stokes equation) 3 components in Cartesian coordinates

$$\rho \left(\frac{\partial v_x}{\partial t} + v_x \frac{\partial v_x}{\partial x} + v_y \frac{\partial v_x}{\partial y} + v_z \frac{\partial v_x}{\partial z} \right) = -\frac{\partial P}{\partial x} + \mu \left(\frac{\partial^2 v_x}{\partial x^2} + \frac{\partial^2 v_x}{\partial y^2} + \frac{\partial^2 v_x}{\partial z^2} \right) + \rho g_x$$

$$\rho \left(\frac{\partial v_y}{\partial t} + v_x \frac{\partial v_y}{\partial x} + v_y \frac{\partial v_y}{\partial y} + v_z \frac{\partial v_y}{\partial z} \right) = -\frac{\partial P}{\partial y} + \mu \left(\frac{\partial^2 v_y}{\partial x^2} + \frac{\partial^2 v_y}{\partial y^2} + \frac{\partial^2 v_y}{\partial z^2} \right) + \rho g_y$$

$$\rho \left(\frac{\partial v_z}{\partial t} + v_x \frac{\partial v_z}{\partial x} + v_y \frac{\partial v_z}{\partial y} + v_z \frac{\partial v_z}{\partial z} \right) = -\frac{\partial P}{\partial z} + \mu \left(\frac{\partial^2 v_z}{\partial x^2} + \frac{\partial^2 v_z}{\partial y^2} + \frac{\partial^2 v_z}{\partial z^2} \right) + \rho g_z$$

Steady

Equation of Motion for incompressible, Newtonian fluid (Navier-Stokes equation), 3 components in cylindrical coordinates

$$\rho \left(\frac{\partial v_r}{\partial t} + v_r \frac{\partial v_r}{\partial r} + \frac{v_\theta}{r} \frac{\partial v_r}{\partial \theta} - \frac{v_\theta^2}{r} + v_z \frac{\partial v_r}{\partial z} \right) = -\frac{\partial P}{\partial r} + \mu \left(\frac{\partial}{\partial r} \left(\frac{1}{r} \frac{\partial (r v_r)}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 v_r}{\partial \theta^2} - \frac{2}{r^2} \frac{\partial v_\theta}{\partial \theta} + \frac{\partial^2 v_r}{\partial z^2} \right) + \rho g_r$$

$$\rho \left(\frac{\partial v_\theta}{\partial t} + v_r \frac{\partial v_\theta}{\partial r} + \frac{v_\theta}{r} \frac{\partial v_\theta}{\partial \theta} + \frac{v_r v_\theta}{r} + v_z \frac{\partial v_\theta}{\partial z} \right) = -\frac{1}{r} \frac{\partial P}{\partial \theta} + \mu \left(\frac{\partial}{\partial r} \left(\frac{1}{r} \frac{\partial (r v_\theta)}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 v_\theta}{\partial \theta^2} + \frac{2}{r^2} \frac{\partial v_r}{\partial \theta} + \frac{\partial^2 v_\theta}{\partial z^2} \right) + \rho g_\theta$$

$$\rho \left(\frac{\partial v_z}{\partial t} + v_r \frac{\partial v_z}{\partial r} + \frac{v_\theta}{r} \frac{\partial v_z}{\partial \theta} + v_z \frac{\partial v_z}{\partial z} \right) = -\frac{\partial P}{\partial z} + \mu \left(\frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial v_z}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 v_z}{\partial \theta^2} + \frac{\partial^2 v_z}{\partial z^2} \right) + \rho g_z$$

Equation of Motion for incompressible, Newtonian fluid (Navier-Stokes equation), 3 components in spherical coordinates

$$\rho \left(\frac{\partial v_r}{\partial t} + v_r \frac{\partial v_r}{\partial r} + \frac{v_\theta}{r} \frac{\partial v_r}{\partial \theta} + \frac{v_\phi}{r \sin \theta} \frac{\partial v_r}{\partial \phi} - \frac{v_\theta^2 + v_\phi^2}{r} \right) = -\frac{\partial P}{\partial r} + \mu \left(\frac{\partial}{\partial r} \left(\frac{1}{r^2} \frac{\partial}{\partial r} (r^2 v_r) \right) + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial v_r}{\partial \theta} \right) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2 v_r}{\partial \phi^2} - \frac{2}{r^2 \sin \theta} \frac{\partial}{\partial \theta} (v_\theta \sin \theta) - \frac{2}{r^2 \sin \theta} \frac{\partial v_\phi}{\partial \phi} \right) + \rho g_r$$

$$\rho \left(\frac{\partial v_\theta}{\partial t} + v_r \frac{\partial v_\theta}{\partial r} + \frac{v_\theta}{r} \frac{\partial v_\theta}{\partial \theta} + \frac{v_\phi}{r \sin \theta} \frac{\partial v_\theta}{\partial \phi} + \frac{v_r v_\theta}{r} - \frac{v_\phi^2 \cot \theta}{r} \right) = -\frac{1}{r} \frac{\partial P}{\partial \theta} + \mu \left(\frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial v_\theta}{\partial r} \right) + \frac{1}{r^2} \frac{\partial}{\partial \theta} \left(\frac{1}{\sin \theta} \frac{\partial}{\partial \theta} (v_\theta \sin \theta) \right) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2 v_\theta}{\partial \phi^2} + \frac{2}{r^2} \frac{\partial v_r}{\partial \theta} - \frac{2 \cot \theta}{r^2 \sin \theta} \frac{\partial v_\phi}{\partial \phi} \right) + \rho g_\theta$$

$$\rho \left(\frac{\partial v_\phi}{\partial t} + v_r \frac{\partial v_\phi}{\partial r} + \frac{v_\theta}{r} \frac{\partial v_\phi}{\partial \theta} + \frac{v_\phi}{r \sin \theta} \frac{\partial v_\phi}{\partial \phi} + \frac{v_r v_\phi}{r} + \frac{v_\theta v_\phi \cot \theta}{r} \right) = -\frac{1}{r \sin \theta} \frac{\partial P}{\partial \phi} + \mu \left(\frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial v_\phi}{\partial r} \right) + \frac{1}{r^2} \frac{\partial}{\partial \theta} \left(\frac{1}{\sin \theta} \frac{\partial}{\partial \theta} (v_\phi \sin \theta) \right) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2 v_\phi}{\partial \phi^2} + \frac{2}{r^2 \sin \theta} \frac{\partial v_r}{\partial \phi} + \frac{2 \cot \theta}{r^2 \sin \theta} \frac{\partial v_\theta}{\partial \phi} \right) + \rho g_\phi$$

Note: the r-component of the Navier-Stokes equation in spherical coordinates may be simplified by adding $0 = \frac{2}{r} \nabla \cdot \underline{v}$ to the component shown above. This term is zero due to the continuity equation (mass conservation). See Bird et. al.

References:

1. R. B. Bird, W. E. Stewart, and E. N. Lightfoot, *Transport Phenomena*, 2nd edition, Wiley: NY, 2002.
2. R. B. Bird, R. C. Armstrong, and O. Hassager, *Dynamics of Polymeric Fluids: Volume 1 Fluid Mechanics*, Wiley: NY, 1987

Equation of Motion for incompressible, Newtonian fluid (Navier-Stokes equation) 3 components in Cartesian coordinates

$$\begin{aligned} \rho \left(\frac{\partial v_x}{\partial t} + v_x \frac{\partial v_x}{\partial x} + v_y \frac{\partial v_x}{\partial y} + v_z \frac{\partial v_x}{\partial z} \right) &= -\frac{\partial P}{\partial x} + \mu \left(\frac{\partial^2 v_x}{\partial x^2} + \frac{\partial^2 v_x}{\partial y^2} + \frac{\partial^2 v_x}{\partial z^2} \right) + \rho g_x \\ \rho \left(\frac{\partial v_y}{\partial t} + v_x \frac{\partial v_y}{\partial x} + v_y \frac{\partial v_y}{\partial y} + v_z \frac{\partial v_y}{\partial z} \right) &= -\frac{\partial P}{\partial y} + \mu \left(\frac{\partial^2 v_y}{\partial x^2} + \frac{\partial^2 v_y}{\partial y^2} + \frac{\partial^2 v_y}{\partial z^2} \right) + \rho g_y \\ \rho \left(\frac{\partial v_z}{\partial t} + v_x \frac{\partial v_z}{\partial x} + v_y \frac{\partial v_z}{\partial y} + v_z \frac{\partial v_z}{\partial z} \right) &= -\frac{\partial P}{\partial z} + \mu \left(\frac{\partial^2 v_z}{\partial x^2} + \frac{\partial^2 v_z}{\partial y^2} + \frac{\partial^2 v_z}{\partial z^2} \right) + \rho g_z \end{aligned}$$

Equation of Motion for incompressible, Newtonian fluid (Navier-Stokes equation), 3 components in cylindrical coordinates

$$\begin{aligned} \rho \left(\frac{\partial v_r}{\partial t} + v_r \frac{\partial v_r}{\partial r} + \frac{v_\theta}{r} \frac{\partial v_r}{\partial \theta} - \frac{v_\theta^2}{r} + v_z \frac{\partial v_r}{\partial z} \right) &= -\frac{\partial P}{\partial r} + \mu \left(\frac{\partial}{\partial r} \left(\frac{1}{r} \frac{\partial (rv_r)}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 v_r}{\partial \theta^2} - \frac{2}{r^2} \frac{\partial v_\theta}{\partial \theta} + \frac{\partial^2 v_r}{\partial z^2} \right) + \rho g_r \\ \rho \left(\frac{\partial v_\theta}{\partial t} + v_r \frac{\partial v_\theta}{\partial r} + \frac{v_\theta}{r} \frac{\partial v_\theta}{\partial \theta} + \frac{v_r v_\theta}{r} + v_z \frac{\partial v_\theta}{\partial z} \right) &= -\frac{1}{r} \frac{\partial P}{\partial \theta} + \mu \left(\frac{\partial}{\partial r} \left(\frac{1}{r} \frac{\partial (rv_\theta)}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 v_\theta}{\partial \theta^2} + \frac{2}{r^2} \frac{\partial v_r}{\partial \theta} + \frac{\partial^2 v_\theta}{\partial z^2} \right) + \rho g_\theta \\ \rho \left(\frac{\partial v_z}{\partial t} + v_r \frac{\partial v_z}{\partial r} + \frac{v_\theta}{r} \frac{\partial v_z}{\partial \theta} + v_z \frac{\partial v_z}{\partial z} \right) &= -\frac{\partial P}{\partial z} + \mu \left(\frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial v_z}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 v_z}{\partial \theta^2} + \frac{\partial^2 v_z}{\partial z^2} \right) + \rho g_z \end{aligned}$$

Handwritten notes: "Stokes", "g", "0", "sum", "0", "g"

Equation of Motion for incompressible, Newtonian fluid (Navier-Stokes equation), 3 components in spherical coordinates

$$\begin{aligned} \rho \left(\frac{\partial v_r}{\partial t} + v_r \frac{\partial v_r}{\partial r} + \frac{v_\theta}{r} \frac{\partial v_r}{\partial \theta} + \frac{v_\phi}{r \sin \theta} \frac{\partial v_r}{\partial \phi} - \frac{v_\theta^2 + v_\phi^2}{r} \right) &= -\frac{\partial P}{\partial r} + \mu \left(\frac{\partial}{\partial r} \left(\frac{1}{r^2} \frac{\partial}{\partial r} (r^2 v_r) \right) + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial v_r}{\partial \theta} \right) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2 v_r}{\partial \phi^2} - \frac{2}{r^2 \sin \theta} \frac{\partial}{\partial \theta} (v_\theta \sin \theta) - \frac{2}{r^2 \sin \theta} \frac{\partial v_\phi}{\partial \phi} \right) + \rho g_r \\ \rho \left(\frac{\partial v_\theta}{\partial t} + v_r \frac{\partial v_\theta}{\partial r} + \frac{v_\theta}{r} \frac{\partial v_\theta}{\partial \theta} + \frac{v_\phi}{r \sin \theta} \frac{\partial v_\theta}{\partial \phi} + \frac{v_r v_\theta}{r} - \frac{v_\phi^2 \cot \theta}{r} \right) &= -\frac{1}{r} \frac{\partial P}{\partial \theta} + \mu \left(\frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial v_\theta}{\partial r} \right) + \frac{1}{r^2} \frac{\partial}{\partial \theta} \left(\frac{1}{\sin \theta} \frac{\partial}{\partial \theta} (v_\theta \sin \theta) \right) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2 v_\theta}{\partial \phi^2} + \frac{2}{r^2} \frac{\partial v_r}{\partial \theta} - \frac{2 \cot \theta}{r^2 \sin \theta} \frac{\partial v_\phi}{\partial \phi} \right) + \rho g_\theta \\ \rho \left(\frac{\partial v_\phi}{\partial t} + v_r \frac{\partial v_\phi}{\partial r} + \frac{v_\theta}{r} \frac{\partial v_\phi}{\partial \theta} + \frac{v_\phi}{r \sin \theta} \frac{\partial v_\phi}{\partial \phi} + \frac{v_r v_\phi}{r} + \frac{v_\theta v_\phi \cot \theta}{r} \right) &= -\frac{1}{r \sin \theta} \frac{\partial P}{\partial \phi} + \mu \left(\frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial v_\phi}{\partial r} \right) + \frac{1}{r^2} \frac{\partial}{\partial \theta} \left(\frac{1}{\sin \theta} \frac{\partial}{\partial \theta} (v_\phi \sin \theta) \right) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2 v_\phi}{\partial \phi^2} + \frac{2}{r^2 \sin \theta} \frac{\partial v_r}{\partial \phi} + \frac{2 \cot \theta}{r^2 \sin \theta} \frac{\partial v_\theta}{\partial \phi} \right) + \rho g_\phi \end{aligned}$$

Handwritten notes: "g = (0, 0, g)", "0", "sum", "0", "g", "0"

Note: the r -component of the Navier-Stokes equation in spherical coordinates may be simplified by adding $0 = \frac{2}{r} \nabla \cdot \underline{v}$ to the component shown above. This term is zero due to the continuity equation (mass conservation). See Bird et. al.

References:

1. R. B. Bird, W. E. Stewart, and E. N. Lightfoot, *Transport Phenomena*, 2nd edition, Wiley: NY, 2002.
2. R. B. Bird, R. C. Armstrong, and O. Hassager, *Dynamics of Polymeric Fluids: Volume 1 Fluid Mechanics*, Wiley: NY, 1987

r-component NS:

$$0 = -\frac{\partial P}{\partial r}$$

\Rightarrow

pressure does
not vary in
r-dir

θ -component of NS:

$$0 = -\frac{1}{r} \frac{\partial P}{\partial \theta}$$

$$\Rightarrow \frac{\partial P}{\partial \theta} = 0$$

\Rightarrow

P does not
vary in θ
dir

4

z-component of NS

⑤

$$0 = -\frac{\partial P}{\partial z} + \mu \left(\frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{dV_z}{dr} \right) \right) + \rho g$$

$P = P(z)$ only

$V_z = V_z(r)$ only

2 functions of
different
independent
variables = ?

$$\underbrace{\frac{dP}{dz} - \rho g}_{\text{only a function of } z} = \underbrace{\mu \frac{1}{r} \frac{d}{dr} \left(r \frac{dV_z}{dr} \right)}_{\text{only a function of } r} = \underbrace{\quad}_{\text{constant}}$$

Separation of Variables

④

only a function of z

$$\frac{dP}{dz} - \rho g = \lambda$$

$$\frac{dP}{dz} = (\lambda + \rho g)$$

$$P = (\lambda + \rho g)z + C_1$$

BC: $z=0 \quad P=P_0$

$z=L \quad P=P_L$

Solve for λ, C_1

only a function of r

$$\mu \frac{1}{r} \frac{d}{dr} \left(r \frac{dv_z}{dr} \right) = \lambda$$

$$\frac{d}{dr} \left(r \frac{dv_z}{dr} \right) = \left(\frac{\lambda}{\mu} \right) r$$

$\equiv \Phi$

$$\frac{d\Phi}{dr} = \left(\frac{\lambda}{\mu} \right) r$$

$$\Phi = \left(\frac{\lambda}{\mu} \right) \frac{r^2}{2} + C_2$$

$$r \frac{dV_z}{dr} = \overline{\Phi} = \frac{\lambda}{2\mu} r^2 + C_2 \quad (7)$$

$$\frac{dV_z}{dr} = \frac{\lambda}{2\mu} r + \frac{C_2}{r}$$

Integrate again wrt. r :

$$V_z = \left(\frac{\lambda}{2\mu} \right) \frac{r^2}{2} + C_2 \ln r + C_3$$

B.C.: ?