

Chapter 5: Material Functions

Michigan Tech
(I call these my "tepee cards")

Steady Shear Flow Material Functions

Imposed Kinematics:

$$\underline{\nu} \equiv \begin{pmatrix} \dot{\zeta}(t)x_2 \\ 0 \\ 0 \end{pmatrix}_{123}$$

$$\dot{\zeta}(t) = \dot{\gamma}_0 = \text{constant}$$

Material Stress Response:

Material Functions:

Viscosity $\eta(\dot{\gamma}_0) \equiv \frac{\bar{\tau}_{21}}{\dot{\gamma}_0} = \frac{-\bar{\tau}_{21}}{\dot{\gamma}_0}$

First normal-stress coefficient $\Psi_1(\dot{\gamma}_0) \equiv \frac{\bar{\tau}_{11} - \bar{\tau}_{22}}{\dot{\gamma}_0^2} = \frac{-(\bar{\tau}_{11} - \bar{\tau}_{22})}{\dot{\gamma}_0^2}$

Second normal-stress coefficient $\Psi_2(\dot{\gamma}_0) \equiv \frac{\bar{\tau}_{22} - \bar{\tau}_{33}}{\dot{\gamma}_0^2} = \frac{-(\bar{\tau}_{22} - \bar{\tau}_{33})}{\dot{\gamma}_0^2}$

**CM4650
Polymer Rheology
Michigan Tech**

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3/5/2018

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What are material functions, and why do we need them?

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What are material functions and why do we need them?

NEWTONIAN

Constitutive equation $\underline{\tau} = -\underline{\tilde{\tau}} = -\mu(\nabla \underline{v} + (\nabla \underline{v})^T)$

+

Momentum balance $\rho \left(\frac{\partial \underline{v}}{\partial t} + \underline{v} \cdot \nabla \underline{v} \right) = -\nabla p - \nabla \cdot \underline{\tau} + \rho \underline{g}$

+

Flow scenarios

=

predictions of:

↓

Velocity and pressure fields $\underline{v}, p(x, y, z)$

When we know $\underline{\tau}(\underline{v})$, the flow modeling effort is expended on developing the flow scenario and solving the math.

2

What are material functions and why do we need them?

NON-NEWTONIAN

Constitutive equation $\underline{\tau} = -\underline{\tilde{\tau}} = \underline{\tau}(\underline{v})$?

+

Momentum balance $\rho \left(\frac{\partial \underline{v}}{\partial t} + \underline{v} \cdot \nabla \underline{v} \right) = -\nabla p - \nabla \cdot \underline{\tau} + \rho \underline{g}$

+

Flow scenarios

=

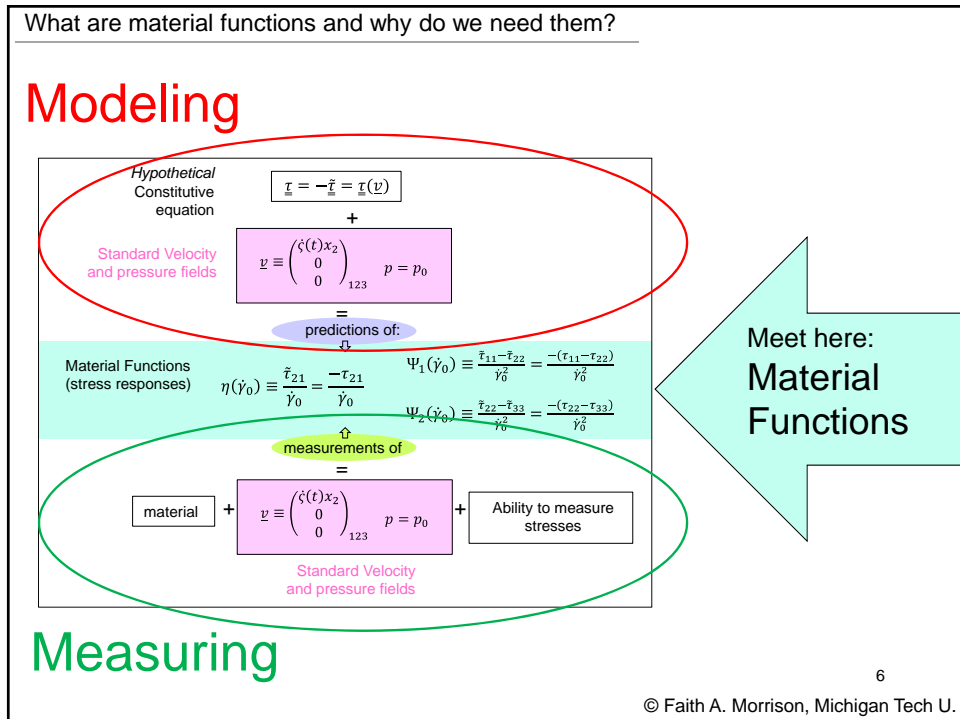
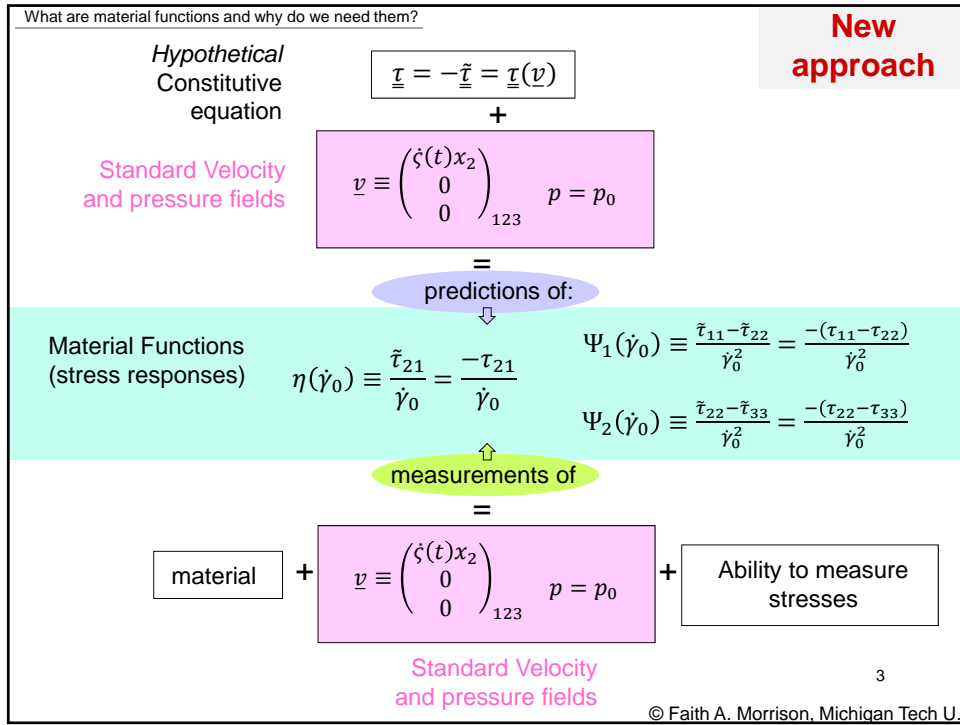
predictions of:

↓

Velocity and pressure fields $\underline{v}, p(x, y, z)$

When we don't know $\underline{\tau}(\underline{v})$, this approach is a nonstarter.

2



What are material functions and why do we need them?

Modeling

Hypothetical Constitutive equation

$$\underline{\tau} = -\underline{\dot{\gamma}} = \underline{\tau}(\underline{\nu})$$

Standard Velocity and pressure fields

$$\underline{\nu} \equiv \begin{pmatrix} \dot{\gamma}(t)x_2 \\ 0 \\ 0 \end{pmatrix}_{123} \quad p = p_0$$

predictions of:

Material Functions (stress responses)

$$\eta(\dot{\gamma}_0) \equiv \frac{\bar{\tau}_{21}}{\dot{\gamma}_0} = \frac{-\tau_{21}}{\dot{\gamma}_0} \quad \Psi_1(\dot{\gamma}_0) \equiv \frac{\bar{\tau}_{11} - \bar{\tau}_{22}}{\dot{\gamma}_0^2} = \frac{-(\tau_{11} - \tau_{22})}{\dot{\gamma}_0^2}$$

$$\Psi_2(\dot{\gamma}_0) \equiv \frac{\bar{\tau}_{22} - \bar{\tau}_{33}}{\dot{\gamma}_0^2} = \frac{-(\tau_{22} - \tau_{33})}{\dot{\gamma}_0^2}$$

measurements of

material + $\underline{\nu} \equiv \begin{pmatrix} \dot{\gamma}(t)x_2 \\ 0 \\ 0 \end{pmatrix}_{123} \quad p = p_0$ + Ability to measure stresses

Standard Velocity and pressure fields

The velocity field is fixed by design (standard flows)

Meet here:
Material Functions

Measuring

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What are material functions and why do we need them?

Modeling

Hypothetical Constitutive equation

$$\underline{\tau} = -\underline{\dot{\gamma}} = \underline{\tau}(\underline{\nu})$$

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measurements of

material + $\underline{\nu} \equiv \begin{pmatrix} \dot{\gamma}(t)x_2 \\ 0 \\ 0 \end{pmatrix}_{123} \quad p = p_0$ + Ability to measure stresses

Standard Velocity and pressure fields

- Approach stress/deformation investigations from two directions (**modeling**, **measuring**) to reveal the physics;
- Material functions organize comparisons

Measuring

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What are material functions and why do we need them?

For non-Newtonian fluids:

- We do not know the stress/deformation relationship ($\underline{\tau}(\underline{v})$)
- We approach stress/deformation investigations from two directions (**modeling**, **measuring**) to reveal the physics;
- Material functions organize comparisons

Hypothetical Constitutive equation: $\underline{\tau} = -\underline{\dot{\gamma}} = \underline{\tau}(\underline{v})$

Standard Velocity and pressure fields: $\underline{v} \equiv \begin{pmatrix} \dot{\gamma}(t)x_2 \\ 0 \\ 0 \end{pmatrix}_{123}, p = p_0$

=

predictions of:

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measurements of

=

material

Standard Velocity and pressure fields: $\underline{v} \equiv \begin{pmatrix} \dot{\gamma}(t)x_2 \\ 0 \\ 0 \end{pmatrix}_{123}, p = p_0$

Ability to measure stresses

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Investigating Stress/Deformation Relationships (Rheology)

For non-Newtonian fluids:

- We do not know the stress/deformation relationship ($\underline{\tau}(\underline{v})$)
- We approach stress/deformation investigations from two directions (**modeling**, **measuring**) to reveal the physics;
- Material functions organize comparisons

(7) (4) (2)

(5) (1)

(6) (3)

What are material functions and why do we need them?

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=

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measurements of

=

material

Standard Velocity and pressure fields: $\underline{v} \equiv \begin{pmatrix} \dot{\gamma}(t)x_2 \\ 0 \\ 0 \end{pmatrix}_{123}, p = p_0$

Ability to measure stresses

1. Choose a material function
2. Predict what Newtonian fluids would do
3. See what non-Newtonian fluids **do**
4. Hypothesize a $\underline{\tau}(\underline{v})$
5. Predict the material function
6. Compare with what non-Newtonian fluids **do**
7. Reflect, **learn**, revise model, repeat.

Let's get started:

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Investigating Stress/Deformation Relationships (Rheology)

1. Choose a material function
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7. Reflect, **learn**, revise model, repeat.

1) Choose a material function

Kinematics

1. Choice of flow (shear or elongation)

$$\underline{v} = \begin{pmatrix} \dot{\zeta}(t)x_2 \\ 0 \\ 0 \end{pmatrix}_{123} \quad \underline{v} = \begin{pmatrix} -\frac{1}{2}\dot{\epsilon}(t)x_1 \\ -\frac{1}{2}\dot{\epsilon}(t)x_2 \\ \dot{\epsilon}(t)x_3 \end{pmatrix}_{123}$$

2. Choice of time dependence of $\dot{\zeta}(t)$ or $\dot{\epsilon}(t)$

3. Material functions definitions: will be based on τ_{21} , N_1 , N_2 in shear or $\tau_{22} - \tau_{11}$, $\tau_{22} - \tau_{11}$ in elongational flows.

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Steady Shear Flow Material Functions

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(I call these my "recipe cards")

Imposed Kinematics:

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$\dot{\zeta}(t) = \dot{\gamma}_0 = \text{constant}$

Material Stress Response:

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Investigating Stress/Deformation Relationships (Rheology)

→

1. Choose a material function
2. Predict what Newtonian fluids would do
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4. Hypothesize a $\underline{\tau}(\underline{v})$
5. Predict the material function
6. Compare with what non-Newtonian fluids **do**
7. Reflect, **learn**, revise model, repeat.

2) Predict what **Newtonian** fluids would do

How do we predict material functions?

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What are material functions and why do we need them?

Constitutive equation $\underline{\tau} = -\tilde{\underline{\tau}} = \underline{\tau}(\underline{v})$

+

Standard Velocity and pressure fields $\underline{v} \equiv \begin{pmatrix} \zeta(t)x_2 \\ 0 \\ 0 \end{pmatrix}_{123} \quad p = p_0$

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predictions of:

↓

Material Functions (stress responses) $\eta(\dot{\gamma}_0) \equiv \frac{\tilde{\tau}_{21}}{\dot{\gamma}_0} = \frac{-\tau_{21}}{\dot{\gamma}_0}$

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New Approach

How do we predict material functions?

We must know the Constitutive Equation.

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Investigating **Stress/Deformation Relationships (Rheology)**

→

1. Choose a material function
2. Predict what Newtonian fluids would do
3. See what non-Newtonian fluids **do**
4. Hypothesize a $\underline{\tau}(\underline{v})$
5. Predict the material function
6. Compare with what non-Newtonian fluids **do**
7. Reflect, **learn**, revise model, repeat.

2) Predict what **Newtonian** fluids would do

What does the **Newtonian** Fluid model predict in steady shearing?

$$\underline{\underline{\tau}} = -\mu \underline{\underline{\dot{\gamma}}} = -\mu [\nabla \underline{v} + (\nabla \underline{v})^T]$$

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Investigating **Stress/Deformation Relationships (Rheology)**

What does the **Newtonian** Fluid model predict in steady shearing?

$$\underline{\underline{\tau}} = -\mu \underline{\underline{\dot{\gamma}}} = -\mu [\nabla \underline{v} + (\nabla \underline{v})^T]$$

You try.

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Investigating Stress/Deformation Relationships (Rheology)

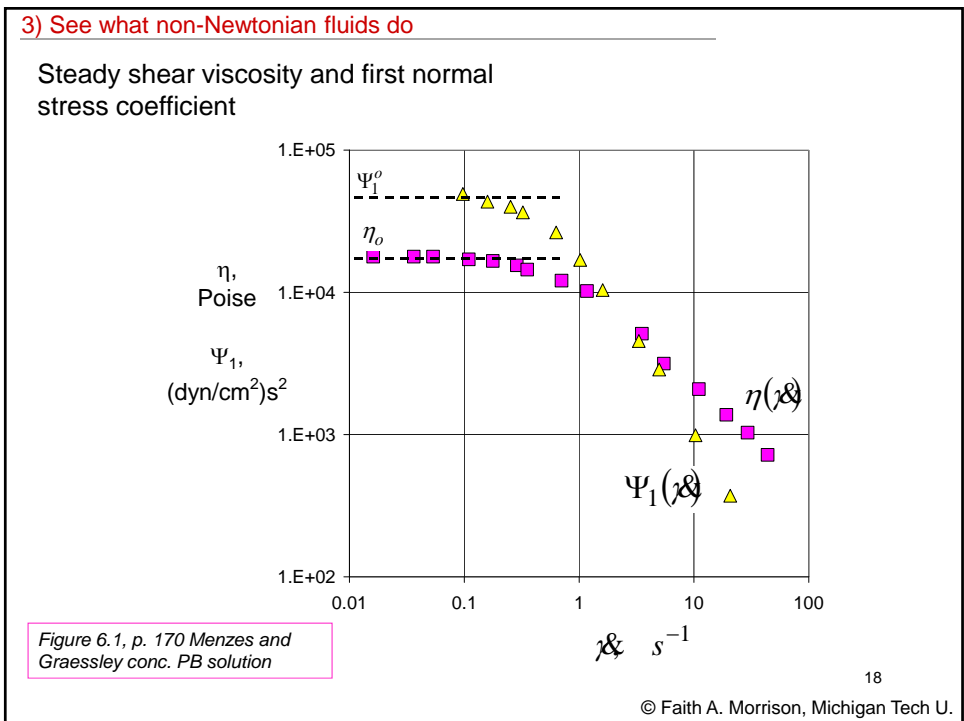
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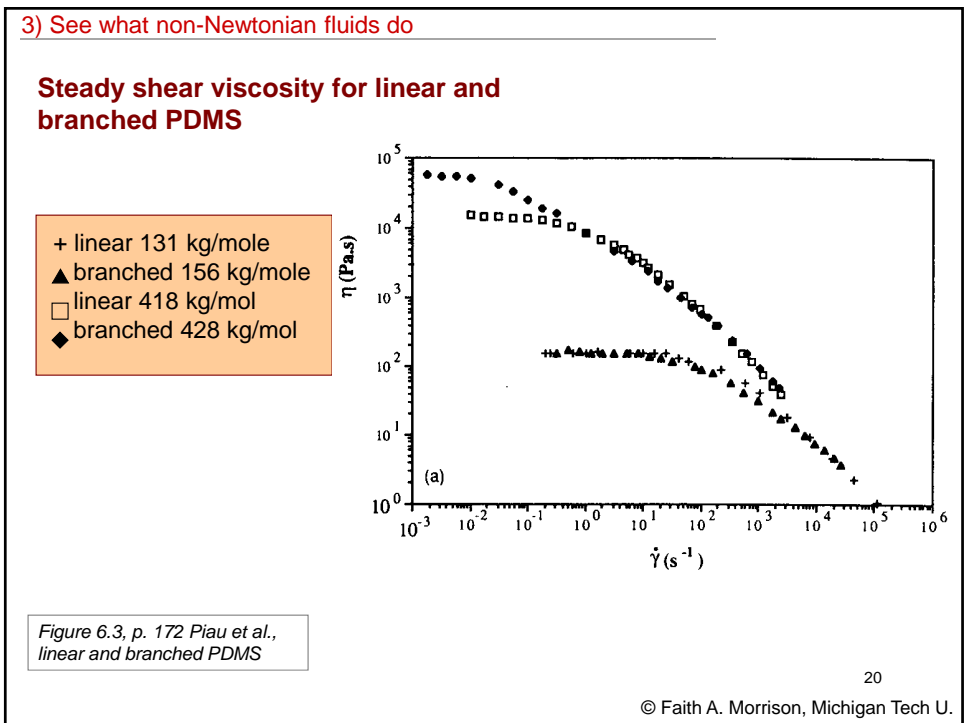
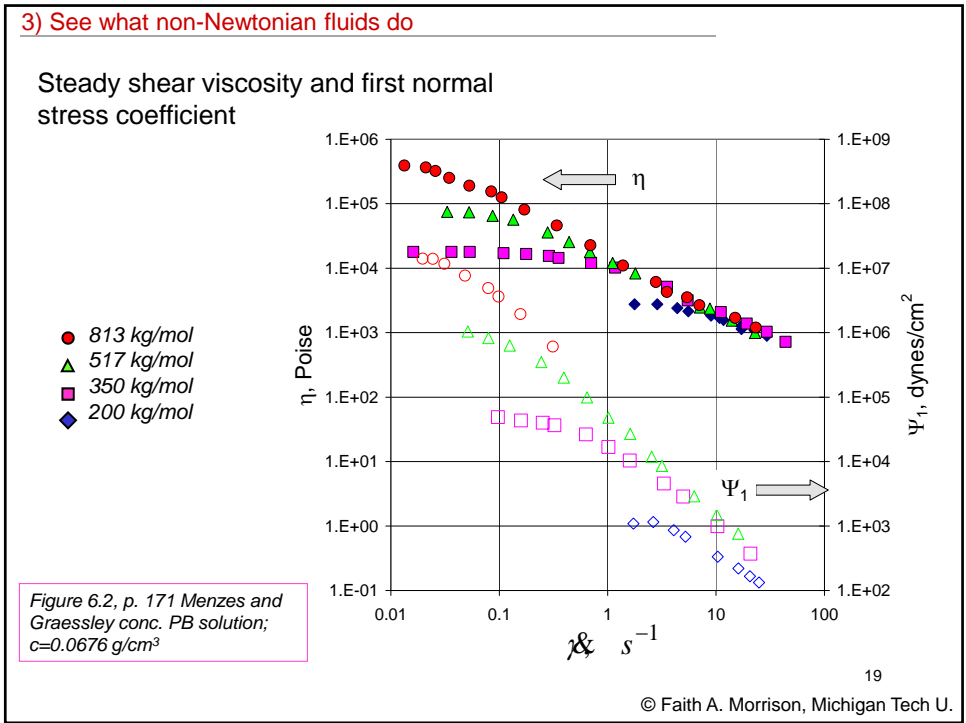
3) See what non-Newtonian fluids do

*What do we **measure** for these material functions?*

(for polymer solutions, for example)

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3) See what non-Newtonian fluids do

Steady shear viscosity and first and **second** normal stress coefficient

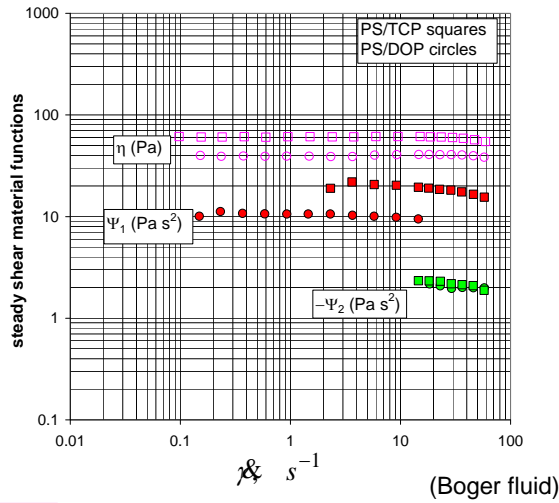


Figure 6.6, p. 174 Magda et al.; Polystyrene solns

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Investigating **Stress/Deformation Relationships (Rheology)**

1. Choose a material function
2. Predict what Newtonian fluids would do
3. See what non-Newtonian fluids **do**
4. Hypothesize a $\underline{\tau}(\underline{\nu})$
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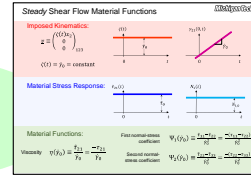
4) Hypothesize a $\underline{\tau}(\underline{\nu})$

(how do we do **that**, exactly?)

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4) Hypothesize a $\underline{\tau}(\underline{\nu})$

What have the investigations of the **steady shear** material functions taught us so far?



- Newtonian constitutive equation is inadequate
 1. Predicts constant shear viscosity (does not predict rate dependence)
 2. Predicts no shear normal stresses (a nonlinear effect; these stresses are generated for many fluids)
- Behavior depends on the material (chemical structure, molecular weight, concentration)

4) Hypothesize a $\underline{\tau}(\underline{\nu})$

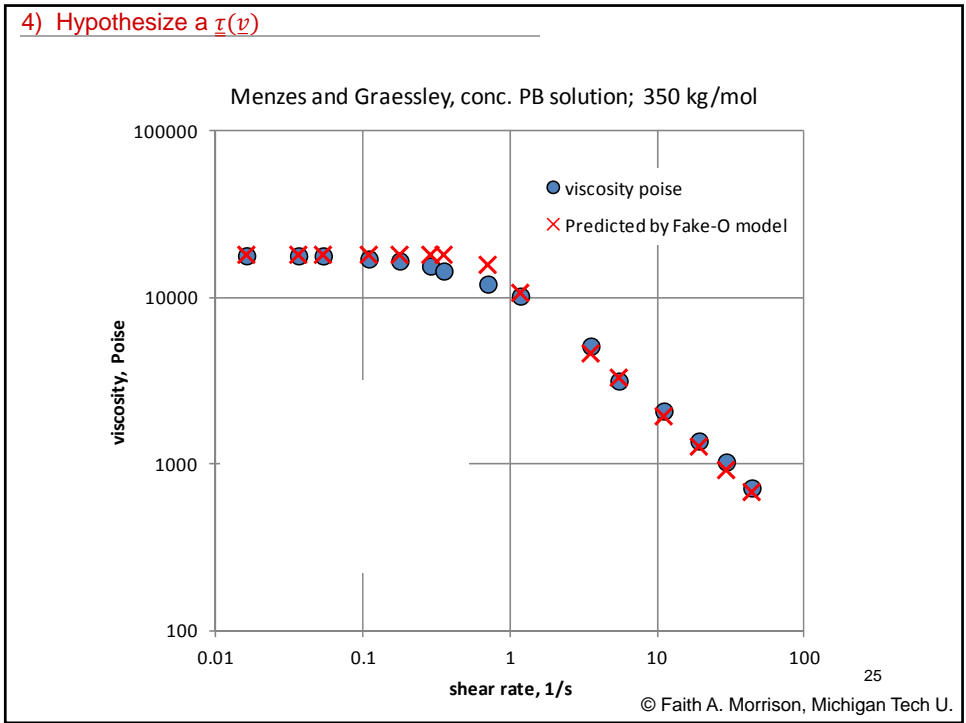
Can we fix the Newtonian Constitutive Equation?

$$\underline{\tau} = -\mu \left[\nabla \underline{\nu} + (\nabla \underline{\nu})^T \right]$$

Let's replace μ with a function of shear rate because we want to predict a rate dependence

$$\underline{\tau} = -(\text{function of } \dot{\gamma}_0) \underline{\dot{\nu}}$$

New hypothesis for $\underline{\tau}(\underline{\nu})$



What are material functions and why do we need them?

Constitutive equation $\underline{\tau} = -\underline{\tilde{\tau}} = \underline{\tau}(\underline{v})$ ← We are guessing this

Standard Velocity and pressure fields $\underline{v} \equiv \begin{pmatrix} \zeta(t)x_2 \\ 0 \\ 0 \end{pmatrix}_{123} \quad p = p_0$

= predictions of:

Material Functions (stress responses)

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Investigating Stress/Deformation Relationships (Rheology)

1. Choose a material function
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4. Hypothesize a $\underline{\tau}(\underline{v})$
5. Predict the material function
6. Compare with what non-Newtonian fluids **do**
7. Reflect, **learn**, revise model, repeat.

→

5) Predict the material function (with new $\underline{\tau}(\underline{v})$)

What does this model predict for steady shear viscosity?

$$\underline{\tau} = -M(\dot{\gamma}_0)[\nabla \underline{v} + (\nabla \underline{v})^T]$$

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5) Predict the material function _____

What does this model predict for steady shear viscosity?

$$\underline{\tau} = -M(\dot{\gamma}_0)[\nabla \underline{v} + (\nabla \underline{v})^T]$$

You try.

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5) Predict the material function _____

What does this model predict for steady shear viscosity?

$$\underline{\tau} = -M(\dot{\gamma}_0)[\nabla \underline{v} + (\nabla \underline{v})^T]$$

Answer:

$$\eta = M(\dot{\gamma}_0)$$

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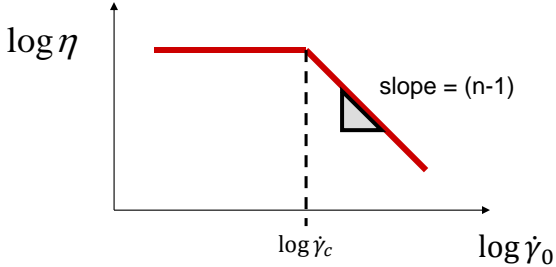
5) Predict the material function _____

If we choose:

$$M(\dot{\gamma}_0) = \begin{cases} M_0 & \dot{\gamma}_0 > \dot{\gamma}_c \\ m\dot{\gamma}_0^{n-1} & \dot{\gamma}_0 \geq \dot{\gamma}_c \end{cases}$$

(we are forcing the observed rate dependence)

Fake-O Model®



Problem solved!
The model and the experiments for $\eta(\dot{\gamma})$ match.

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5) Predict the material function

But what about the normal stresses?

$$\underline{\underline{\tau}} = -M(\dot{\gamma}_0)[\nabla \underline{v} + (\nabla \underline{v})^T]$$

$$M(\dot{\gamma}_0) = \begin{cases} M_0 & \dot{\gamma}_0 > \dot{\gamma}_c \\ m\dot{\gamma}_0^{n-1} & \dot{\gamma}_0 \geq \dot{\gamma}_c \end{cases}$$

$$\nabla v = \begin{pmatrix} 0 & 0 & 0 \\ \dot{\gamma}_0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}_{123} \quad \underline{\underline{\dot{\gamma}}} = \begin{pmatrix} 0 & \dot{\gamma}_0 & 0 \\ \dot{\gamma}_0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}_{123}$$

$$\underline{\underline{\tau}} = \begin{pmatrix} 0 & -M(\dot{\gamma}_0)\dot{\gamma}_0 & 0 \\ -M(\dot{\gamma}_0)\dot{\gamma}_0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}_{123}$$

$\Rightarrow \Psi_1 = \Psi_2 = 0$

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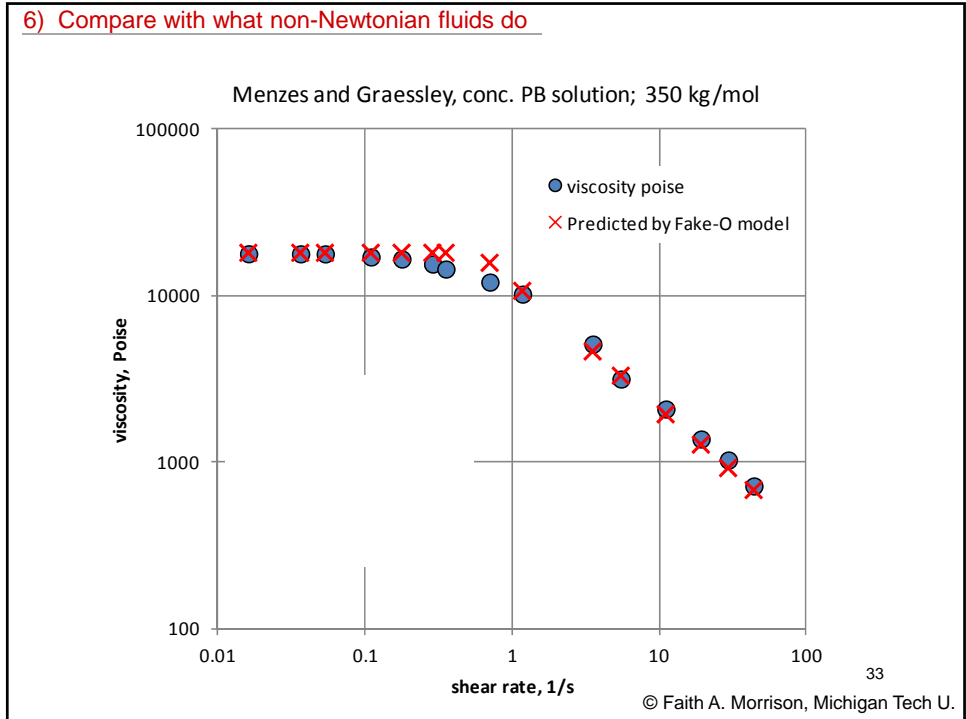
Investigating **Stress/Deformation Relationships (Rheology)**

1. Choose a material function
2. Predict what Newtonian fluids would do
3. See what non-Newtonian fluids **do**
4. Hypothesize a $\underline{\underline{\tau}}(\underline{\underline{v}})$
5. Predict the material function
6. Compare with what non-Newtonian fluids **do**
7. Reflect, **learn**, revise model, repeat.

6) Compare with what non-Newtonian fluids **do**

?

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6) Compare with what non-Newtonian fluids do

Fake-O Model Predictions:

Steady shear:

$$\eta = \begin{cases} M_0 & \dot{\gamma}_0 \leq \dot{\gamma}_c \\ m\dot{\gamma}_0^{n-1} & \dot{\gamma}_0 > \dot{\gamma}_c \end{cases}$$

$$\Psi_1 = 0$$

$$\Psi_2 = 0$$

Polymer Behavior:

$\Psi_1 \neq 0$
 $\Psi_2 \neq 0$

Second normal stress effects: inclined open-channel flow

$\tau_{22} - \tau_{33} > 0$
Extra tension in the 2-direction pulls down the free surface where $\partial v_x / \partial y$ is greatest (see DPL p65).

Newtonian - glycerin
Viscoelastic - 1% soln of polyethylene oxide in water

$N_2 = -N_1/10$

R. I. Tanner, *Engineering Rheology*, Oxford 1985, Figure 3.6 page 104

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6) Compare with what non-Newtonian fluids do

Fake-O Model Predictions: **Steady shear:**

$$\checkmark \eta = \begin{cases} M_0 & \dot{\gamma}_0 \leq \dot{\gamma}_c \\ m\dot{\gamma}_0^{n-1} & \dot{\gamma}_0 > \dot{\gamma}_c \end{cases}$$

$$\times \Psi_1 = 0$$

$$\times \Psi_2 = 0$$

Polymer Behavior:

Second normal stress effects: inclined open-channel flow $\tau_{22} - \tau_{33} > 0$

Extra tension in the 2-direction pulls down the free surface where $\partial v_x / \partial x_2$ is greatest (see DPL p65).

Newtonian - glycerin Viscoelastic - 1% soln of polyethylene oxide in water

$N_2 = -N_1/10$

R. I. Tanner, *Engineering Rheology*, Oxford 1985, Figure 3.6 page 104

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6) Compare with what non-Newtonian fluids do

Why did we get 0 for the normal stresses?

$$\underline{\underline{\tau}} = -M(\dot{\gamma}_0) [\nabla \underline{v} + (\nabla \underline{v})^T]$$

$$M(\dot{\gamma}_0) = \begin{cases} M_0 & \dot{\gamma}_0 > \dot{\gamma}_c \\ m\dot{\gamma}_0^{n-1} & \dot{\gamma}_0 \geq \dot{\gamma}_c \end{cases}$$

$$\underline{\underline{\tau}} = -M(\dot{\gamma}_0) \begin{pmatrix} 0 & \dot{\gamma}_0 & 0 \\ \dot{\gamma}_0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}_{123}$$

$\Rightarrow \Psi_1 = \Psi_2 = 0$

It appears that $\underline{\underline{\tau}}$ should not be simply proportional to $\dot{\underline{\underline{\gamma}}}$

Need to try something else . . .

$$\underline{\underline{\tau}} = -\mu \dot{\underline{\underline{\gamma}}} + \underline{I} f(\underline{v})$$

$$\underline{\underline{\tau}} = f(\underline{v}) \nabla \underline{v} \cdot (\nabla \underline{v})^T$$

$$\underline{\underline{\tau}} = A[\nabla \underline{v} \cdot (\nabla \underline{v})^T] + B \nabla \underline{v} + C (\nabla \underline{v})^T$$

...

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Investigating Stress/Deformation Relationships (Rheology)

1. Choose a material function
2. Predict what Newtonian fluids would do
3. See what non-Newtonian fluids **do**
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5. Predict the material function
6. Compare with what non-Newtonian fluids **do**
7. Reflect, **learn**, revise model, repeat.

➔

7) Reflect, **learn**, revise model, repeat

- ✓ Reflect
- ✓ Learn
- ✓ Revise model
- ✓ Propose new $\underline{\tau}(\underline{\dot{\gamma}})$
- ✓ Repeat cycle....

What are material functions and why do we need them?

- For non-Newtonian fluids:
- We do not know the stress/deformation relationship ($\underline{\tau}(\underline{\dot{\gamma}})$)
- We approach stress/deformation investigations from two directions (**modeling**, **measuring**) to reveal the physics;
- Material functions organize comparisons

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7) Reflect, learn, revise model, repeat

- ✓ Reflect
- ✓ Learn
- ✓ Revise model
- ✓ Propose new $\underline{\tau}(\underline{\dot{\gamma}})$
- ✓ Repeat cycle....

What shall we guess next?

To sort out how to fix the Newtonian equation, we need more observations (to give us ideas).

Let's try another material function that's not a steady flow (but stick to shear).

1) Choose a material function

What are material functions and why do we need them?

- For non-Newtonian fluids:
- We do not know the stress/deformation relationship ($\underline{\tau}(\underline{\dot{\gamma}})$)
- We approach stress/deformation investigations from two directions (**modeling**, **measuring**) to reveal the physics;
- Material functions organize comparisons

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Investigating Stress/Deformation Relationships (Rheology)

1. Choose a material function
2. Predict what Newtonian fluids would do
3. See what non-Newtonian fluids **do**
4. Hypothesize a $\underline{\tau}(\underline{\nu})$
5. Predict the material function
6. Compare with what non-Newtonian fluids **do**
7. Reflect, **learn**, revise model, repeat.

1) Choose a material function

Kinematics

1. Choice of flow (shear or elongation)

$$\underline{\nu} = \begin{pmatrix} \dot{\zeta}(t)x_2 \\ 0 \\ 0 \end{pmatrix}_{123} \quad \underline{\nu} = \begin{pmatrix} -\frac{1}{2}\dot{\epsilon}(t)x_1 \\ -\frac{1}{2}\dot{\epsilon}(t)x_2 \\ \dot{\epsilon}(t)x_3 \end{pmatrix}_{123}$$
2. Choice of time dependence of $\dot{\zeta}(t)$ or $\dot{\epsilon}(t)$
3. Material functions definitions: will be based on τ_{21} , N_1 , N_2 in shear or $\tau_{22} - \tau_{11}$, $\tau_{22} - \tau_{11}$ in elongational flows.

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Start-up of Steady Shear Flow Material Functions

Imposed Kinematics:

$$\underline{\nu} \equiv \begin{pmatrix} \dot{\zeta}(t)x_2 \\ 0 \\ 0 \end{pmatrix}_{123}$$

$$\dot{\zeta}(t) = \begin{cases} 0 & t < 0 \\ \dot{\gamma}_0 & t \geq 0 \end{cases}$$

Material Stress Response:

Material Functions:

Shear stress growth function $\eta^+(t, \dot{\gamma}_0) \equiv \frac{\bar{\tau}_{21}(t)}{\dot{\gamma}_0} = \frac{-\tau_{21}(t)}{\dot{\gamma}_0}$

First normal-stress growth coefficient $\Psi_1^+(t, \dot{\gamma}_0) \equiv \frac{\bar{\tau}_{11} - \bar{\tau}_{22}}{\dot{\gamma}_0^2}$

Second normal-stress growth coefficient $\Psi_2^+(t, \dot{\gamma}_0) \equiv \frac{\bar{\tau}_{22} - \bar{\tau}_{33}}{\dot{\gamma}_0^2}$

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Investigating Stress/Deformation Relationships (Rheology)

1. Choose a material function
2. Predict what Newtonian fluids would do
3. See what non-Newtonian fluids **do**
4. Hypothesize a $\underline{\tau}(\underline{v})$
5. Predict the material function
6. Compare with what non-Newtonian fluids **do**
7. Reflect, **learn**, revise model, repeat.

2) Predict what Newtonian fluids would do

What does the **Newtonian** Fluid model predict in start-up of steady shearing?

$$\underline{\tau} = -\mu \left[\nabla \underline{v} + (\nabla \underline{v})^T \right]$$

Again, since we know \underline{v} , we can just substitute it into the constitutive equation and calculate the stresses.

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2) Predict what Newtonian fluids would do (round 2)

What does the **Newtonian** Fluid constitutive equation predict in start-up of steady shearing?

$$\underline{\tau} = -\mu \left[\nabla \underline{v} + (\nabla \underline{v})^T \right]$$

You try.

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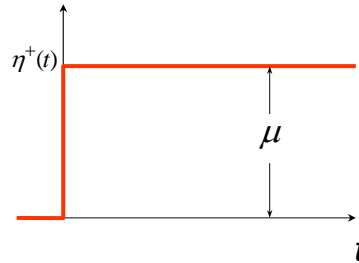
2) Predict what Newtonian fluids would do (round 2)

Material functions predicted for *start-up of steady shearing* of a Newtonian fluid

$$\eta^+(t) = \begin{cases} 0 & t < 0 \\ \mu & t \geq 0 \end{cases}$$

$$\Psi_1^+ \equiv \frac{-(\tau_{11} - \tau_{33})}{\dot{\gamma}_0^2} = 0$$

$$\Psi_2^+ \equiv \frac{-(\tau_{22} - \tau_{33})}{\dot{\gamma}_0^2} = 0$$



Do these predictions match observations?

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Investigating **Stress/Deformation Relationships (Rheology)**



1. Choose a material function
2. Predict what Newtonian fluids would do
3. See what non-Newtonian fluids **do**
4. Hypothesize a $\underline{\tau}(\underline{\gamma})$
5. Predict the material function
6. Compare with what non-Newtonian fluids **do**
7. Reflect, **learn**, revise model, repeat.

3) See what non-Newtonian fluids **do**

What do we **measure** for these material functions?

(for polymer solutions, for example)

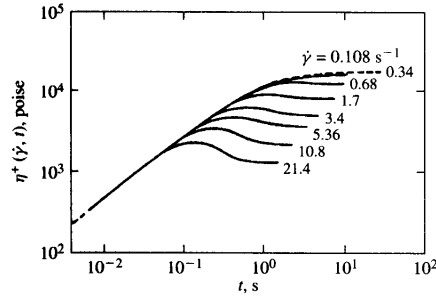
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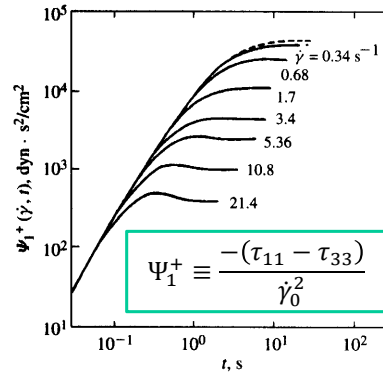
3) See what non-Newtonian fluids do (round 2)

Startup of Steady Shearing

$$\underline{v} \equiv \begin{pmatrix} \dot{\zeta}(t)x_2 \\ 0 \\ 0 \end{pmatrix}_{123} \quad \dot{\zeta}(t) = \begin{cases} 0 & t < 0 \\ \dot{\gamma}_0 & t \geq 0 \end{cases}$$



$$\eta^+(t) = \begin{cases} 0 & t < 0 \\ \mu & t \geq 0 \end{cases}$$

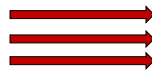


Figures 6.49, 6.50, p. 208 Menezes and Graessley, Polybutadiene soln

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Investigating Stress/Deformation Relationships (Rheology)




1. Choose a material function
2. Predict what Newtonian fluids would do
3. See what non-Newtonian fluids **do**
4. Hypothesize a $\underline{\tau}(\underline{v})$
5. Predict the material function
6. Compare with what non-Newtonian fluids **do**
7. Reflect, **learn**, revise model, repeat.

3) See what non-Newtonian fluids do

What about other non-steady flows?

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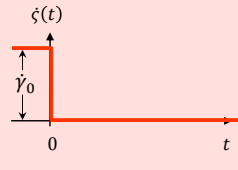
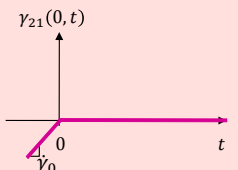
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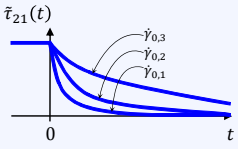
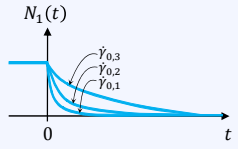
Cessation of Steady Shear Flow Material Functions

Imposed Kinematics:

$$\underline{v} \equiv \begin{pmatrix} \dot{\zeta}(t)x_2 \\ 0 \\ 0 \end{pmatrix}_{123}$$

$$\dot{\zeta}(t) = \begin{cases} \dot{\gamma}_0 & t < 0 \\ 0 & t \geq 0 \end{cases}$$



Material Stress Response:

Material Functions:

Shear stress decay function $\eta^-(t, \dot{\gamma}_0) \equiv \frac{\bar{\tau}_{21}(t)}{\dot{\gamma}_0} = \frac{-\tau_{21}(t)}{\dot{\gamma}_0}$

First normal-stress decay coefficient $\Psi_1^-(t, \dot{\gamma}_0) \equiv \frac{\bar{\tau}_{11} - \bar{\tau}_{22}}{\dot{\gamma}_0^2}$

Second normal-stress decay coefficient $\Psi_2^-(t, \dot{\gamma}_0) \equiv \frac{\bar{\tau}_{22} - \bar{\tau}_{33}}{\dot{\gamma}_0^2}$

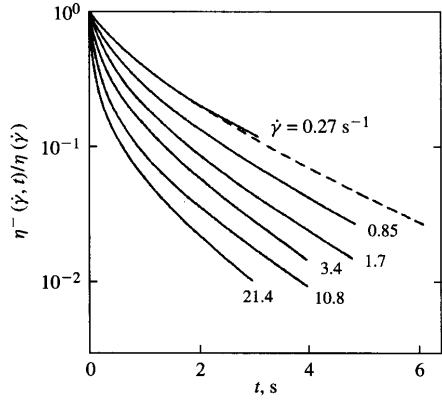
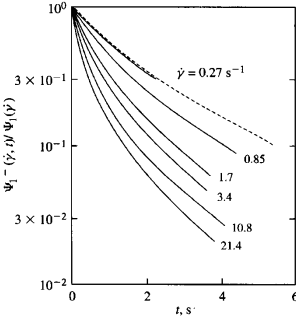
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3) See what non-Newtonian fluids do (round 3)

Cessation of Steady Shearing

$$\underline{v} \equiv \begin{pmatrix} \dot{\zeta}(t)x_2 \\ 0 \\ 0 \end{pmatrix}_{123}$$

$$\dot{\zeta}(t) = \begin{cases} \dot{\gamma}_0 & t < 0 \\ 0 & t \geq 0 \end{cases}$$



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Figures 6.51, 6.52, p. 209
Menezes and Graessley, PB soln

Investigating Stress/Deformation Relationships (Rheology)

1. Choose a material function
2. Predict what Newtonian fluids would do
3. See what non-Newtonian fluids **do**
4. Hypothesize a $\underline{\tau}(\underline{v})$
5. Predict the material function
6. Compare with what non-Newtonian fluids **do**
7. Reflect, **learn**, revise model, repeat.

5) Predict the material function

What does the Fake-O model® predict for start-up and cessation of shear?

$$\underline{\tau} = -M(\dot{\gamma}_0)[\nabla \underline{v} + (\nabla \underline{v})^T]$$

$$M(\dot{\gamma}_0) = \begin{cases} M_0 & \dot{\gamma}_0 > \dot{\gamma}_c \\ m\dot{\gamma}_0^{n-1} & \dot{\gamma}_0 \geq \dot{\gamma}_c \end{cases}$$

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5) Predict the material functions (rounds 2 & 3)

What does the Fake-O model® predict for start-up and cessation of shear?

You try.

$$\underline{\tau} = -M(\dot{\gamma}_0)[\nabla \underline{v} + (\nabla \underline{v})^T]$$

$$M(\dot{\gamma}_0) = \begin{cases} M_0 & \dot{\gamma}_0 > \dot{\gamma}_c \\ m\dot{\gamma}_0^{n-1} & \dot{\gamma}_0 \geq \dot{\gamma}_c \end{cases}$$

2018: Homework 3

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Investigating Stress/Deformation Relationships (Rheology)

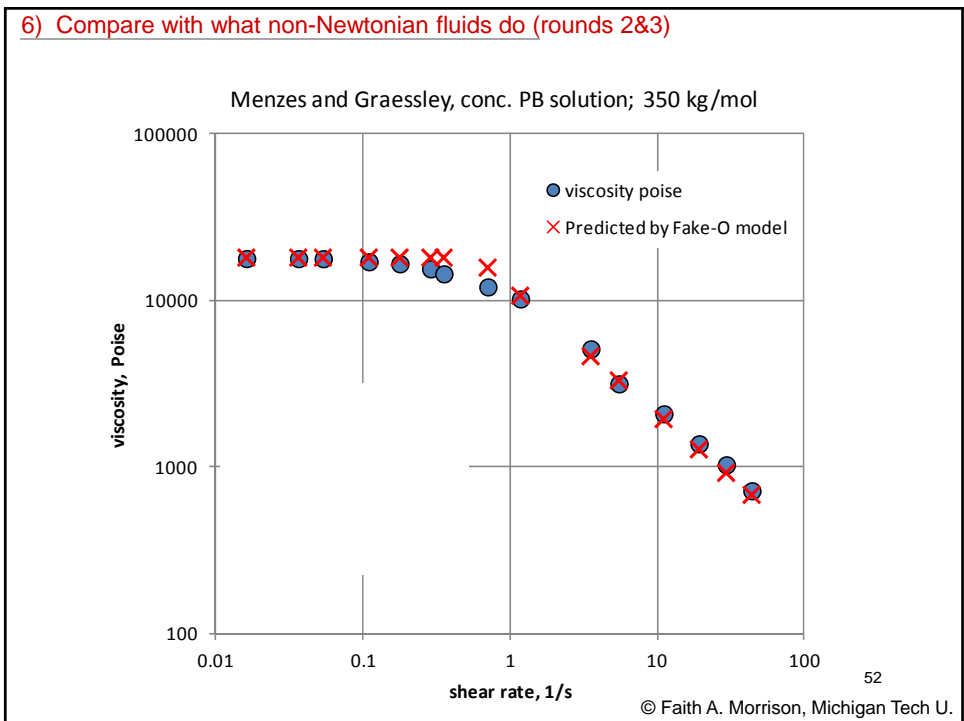
1. Choose a material function
2. Predict what Newtonian fluids would do
3. See what non-Newtonian fluids **do**
4. Hypothesize a $\tau(\dot{\gamma})$
5. Predict the material function
6. Compare with what non-Newtonian fluids **do**
7. Reflect, **learn**, revise model, repeat.

→

6) Compare with what non-Newtonian fluids do

?

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6) Compare with what non-Newtonian fluids do (rounds 2&3)

Fake-O Model Shear Material Function Predictions:

Start-up of steady shear:

$$\eta^+(t) = \begin{cases} 0 & t < 0 \\ M(\dot{\gamma}_0) & t \geq 0 \end{cases}$$

$$\text{where } M(\dot{\gamma}_0) = \begin{cases} M_0 & \dot{\gamma}_0 \leq \dot{\gamma}_c \\ m\dot{\gamma}_0^{n-1} & \dot{\gamma}_0 > \dot{\gamma}_c \end{cases}$$

$$\Psi_1^+(t) = 0$$

$$\Psi_2^+(t) = 0$$

Cessation of steady shear:

$$\eta^-(t) = \begin{cases} M(\dot{\gamma}_0) & t < 0 \\ 0 & t \geq 0 \end{cases}$$

$$\text{where } M(\dot{\gamma}_0) = \begin{cases} M_0 & \dot{\gamma}_0 \leq \dot{\gamma}_c \\ m\dot{\gamma}_0^{n-1} & \dot{\gamma}_0 > \dot{\gamma}_c \end{cases}$$

$$\Psi_1^-(t) = 0$$

$$\Psi_2^-(t) = 0$$

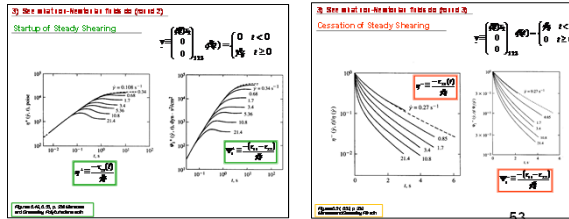
Polymer Behavior:

- captures rate dependence, but,

$$\Psi_1^+ \neq 0$$

$$\Psi_2^+ \neq 0$$

- Also, response is **not instantaneous**



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6) Compare with what non-Newtonian fluids do (rounds 2&3)

$$\underline{\underline{\tau}} = -M(\dot{\gamma}_0)[\nabla \underline{v} + (\nabla \underline{v})^T]$$

Observations

$$M(\dot{\gamma}_0) = \begin{cases} M_0 & \dot{\gamma}_0 > \dot{\gamma}_c \\ m\dot{\gamma}_0^{n-1} & \dot{\gamma}_0 \geq \dot{\gamma}_c \end{cases}$$

- The Fake-O model® predicts an instantaneous stress response, and this is not what is observed for polymers
- The predicted unsteady material functions depend on the shear rate, which is observed for polymers

$$\eta^+ = \eta^+(t, \dot{\gamma}_0)$$

← Progress here

- No shear normal stresses are predicted

6) Compare with what non-Newtonian fluids do (rounds 2&3)

$$\underline{\underline{\tau}} = -M(\dot{\gamma}_0)[\nabla \underline{v} + (\nabla \underline{v})^T]$$

Observations

$$M(\dot{\gamma}_0) = \begin{cases} M_0 & \dot{\gamma}_0 > \dot{\gamma}_c \\ m\dot{\gamma}_0^{n-1} & \dot{\gamma}_0 \leq \dot{\gamma}_c \end{cases}$$

- The Fake-O model® predicts an instantaneous stress response, and this is not what is observed for polymers ← **Lacks memory**
- The predicted unsteady material functions depend on the shear rate, which is observed for polymers

$$\eta^+ = \eta^+(t, \dot{\gamma}_0)$$
← **Progress here**

- No shear normal stresses are predicted ← **Related to nonlinearities**

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Investigating **Stress/Deformation Relationships (Rheology)**

1. Choose a material function
2. Predict what Newtonian fluids would do
3. See what non-Newtonian fluids **do**
4. Hypothesize a $\underline{\tau}(\underline{v})$
5. Predict the material function
6. Compare with what non-Newtonian fluids **do**
7. Reflect, **learn**, revise model, repeat.

7) Reflect, **learn**, revise model, repeat

- ✓ Reflect
- ✓ Learn
- ✓ Revise model
- ✓ Propose new $\underline{\tau}(\underline{v})$
- ✓ Repeat cycle....

What are material functions and why do we need them?

For non-Newtonian fluids:

(7) (4) (2)

(5) (1)

(6) (3)

- We do not know the stress/deformation relationship ($\underline{\tau}(\underline{v})$)
- We approach stress/deformation investigations from two directions (**modeling, measuring**) to reveal the physics;
- Material functions organize comparisons

Hypothetical Constitutive equation: $\underline{\tau} = -\eta \dot{\gamma}$

Standard Velocity and pressure fields: $\underline{v} = \begin{pmatrix} 0 \\ 0 \\ \dot{\gamma} \end{pmatrix}$, $p = p_0$

Material Functions (stress responses): $\eta(\dot{\gamma}_0) = \frac{\tau_{xy}}{\dot{\gamma}_0}$, $\eta_p(\dot{\gamma}_0) = \frac{\tau_{xy}}{\dot{\gamma}_0} = \frac{\tau_{xy}}{\dot{\gamma}_0}$

Material Functions (stress responses): $\eta(\dot{\gamma}_0) = \frac{\tau_{xy}}{\dot{\gamma}_0}$, $\eta_p(\dot{\gamma}_0) = \frac{\tau_{xy}}{\dot{\gamma}_0} = \frac{\tau_{xy}}{\dot{\gamma}_0}$

material: $\underline{\tau} = \begin{pmatrix} 0 \\ 0 \\ \tau_{xy} \end{pmatrix}$, $p = p_0$

Standard Velocity and pressure fields: $\underline{v} = \begin{pmatrix} 0 \\ 0 \\ \dot{\gamma} \end{pmatrix}$, $p = p_0$

Ability to measure stresses

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7) Reflect, learn, revise model, repeat

To proceed to better-designed constitutive equations, we need to know more about material behavior, i.e. we need more material functions to predict, and we need measurements of these material functions.

- More non-steady material functions (material functions that tell us about memory)
- Material functions that tell us about nonlinearity (strain)
- Material functions for a different flow

What are material functions and why do we need them?

- We do not know the stress/deformation relationship $\underline{\tau}(\underline{\underline{\epsilon}})$
- We approach stress/deformation investigations from two directions (**modeling**, **measuring**) to reveal the physics;
- Material functions organize comparisons

Back to step 1

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Investigating Stress/Deformation Relationships (Rheology)

1. Choose a material function
2. Predict what Newtonian fluids would do
3. See what non-Newtonian fluids **do**
4. Hypothesize a $\underline{\tau}(\underline{\underline{\epsilon}})$
5. Predict the material function
6. Compare with what non-Newtonian fluids **do**
7. Reflect, **learn**, revise model, repeat.

1) Choose a material function

Kinematics

1. Choice of flow (shear or elongation)

$$\underline{\underline{v}} = \begin{pmatrix} \zeta(t)x_2 \\ 0 \\ 0 \end{pmatrix}_{123} \quad \underline{\underline{v}} = \begin{pmatrix} -\frac{1}{2}\dot{\epsilon}(t)x_1 \\ -\frac{1}{2}\dot{\epsilon}(t)x_2 \\ \dot{\epsilon}(t)x_3 \end{pmatrix}_{123}$$
2. Choice of time dependence of $\zeta(t)$ or $\dot{\epsilon}(t)$
3. Material functions definitions: will be based on τ_{21} , N_1 , N_2 in shear or $\tau_{22} - \tau_{11}$, $\tau_{22} - \tau_{11}$ in elongational flows.

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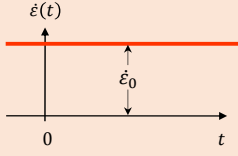
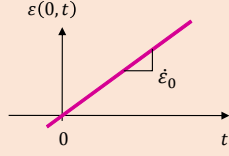
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Steady Elongational Flow Material Functions

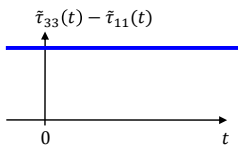
Imposed Kinematics:

$$\underline{v} \equiv \begin{pmatrix} -\frac{1}{2}\dot{\epsilon}(t)x_1 \\ -\frac{1}{2}\dot{\epsilon}(t)x_2 \\ \dot{\epsilon}(t)x_3 \end{pmatrix}_{123}$$

$$\dot{\epsilon}(t) = \dot{\epsilon}_0 = \text{constant}$$

Material Stress Response:



Material Functions:

Elongational Viscosity $\eta_e(\dot{\epsilon}_0) \equiv \frac{\bar{\tau}_{33} - \bar{\tau}_{11}}{\dot{\epsilon}_0} = \frac{-(\tau_{33} - \tau_{11})}{\dot{\epsilon}_0}$

Alternatively, $\bar{\eta}(\dot{\epsilon}_0)$

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2) Predict what Newtonian fluids would do.

1. Choose a material function
2. Predict what Newtonian fluids would do
3. See what non-Newtonian fluids **do**
4. Hypothesize a $\underline{\tau}(\underline{\dot{\gamma}})$
5. Predict the material function
6. Compare with what non-Newtonian fluids **do**
7. Reflect, **learn**, revise model, repeat.

2) Predict what Newtonian fluids would do.

?



$$\underline{\tau} = -\mu \underline{\dot{\gamma}}$$

Steady Elongational Flow Material Functions 

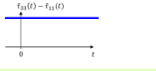
Imposed Kinematics:

$$\underline{v} \equiv \begin{pmatrix} -\frac{1}{2}\dot{\epsilon}(t)x_1 \\ -\frac{1}{2}\dot{\epsilon}(t)x_2 \\ \dot{\epsilon}(t)x_3 \end{pmatrix}_{123}$$

$$\dot{\epsilon}(t) = \dot{\epsilon}_0 = \text{constant}$$

Material Stress Response:




Material Functions:

Elongational Viscosity $\eta_e(\dot{\epsilon}_0) \equiv \frac{\bar{\tau}_{33} - \bar{\tau}_{11}}{\dot{\epsilon}_0} = \frac{-(\tau_{33} - \tau_{11})}{\dot{\epsilon}_0}$

Alternatively, $\bar{\eta}(\dot{\epsilon}_0)$

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3) See what non-Newtonian fluids do



1. Choose a material function
2. Predict what Newtonian fluids would do
3. See what non-Newtonian fluids **do**
4. Hypothesize a $\underline{\tau}(\underline{\gamma})$
5. Predict the material function
6. Compare with what non-Newtonian fluids **do**
7. Reflect, **learn**, revise model, repeat.


3) See what non-Newtonian fluids **do**

?

You try.

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Investigating **Stress/Deformation Relationships (Rheology)**



1. Choose a material function
2. Predict what Newtonian fluids would do
3. See what non-Newtonian fluids **do**
4. Hypothesize a $\underline{\tau}(\underline{\gamma})$
5. Predict the material function
6. Compare with what non-Newtonian fluids **do**
7. Reflect, **learn**, revise model, repeat.

6) Compare with what non-Newtonian fluids **do**

?

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3) See what non-Newtonian fluids do

Steady State Elongation Viscosity

Both tension thinning and thickening are observed.

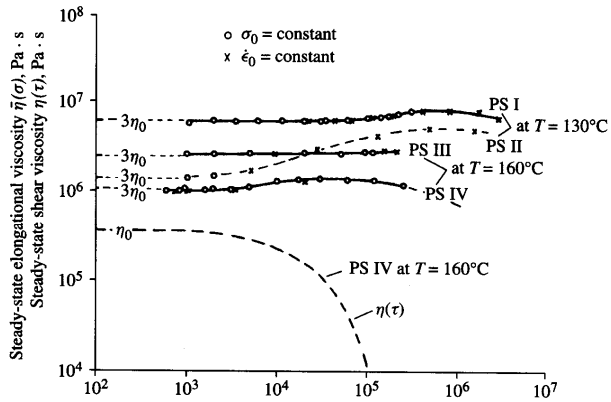


Figure 6.60, p. 215 Munstedt.; PS melt

Trouton ratio: $Tr \equiv \frac{\bar{\eta}}{\eta_0}$

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Investigating Stress/Deformation Relationships (Rheology)

1. Choose a material function
2. Predict what Newtonian fluids would do
3. See what non-Newtonian fluids **do**
4. Hypothesize a $\underline{\tau}(\underline{\nu})$
5. Predict the material function
6. Compare with what non-Newtonian fluids **do**
7. Reflect, **learn**, revise model, repeat.

5) Predict the material function (with new $\underline{\tau}(\underline{\nu})$)

What does the Fake-O[®]-model predict for steady elongational viscosity?

$$\underline{\tau} = -M(\dot{\gamma}_0)[\nabla \underline{\nu} + (\nabla \underline{\nu})^T]$$

$$M(\dot{\gamma}_0) = \begin{cases} M_0 & \dot{\gamma}_0 > \dot{\gamma}_c \\ m\dot{\gamma}_0^{n-1} & \dot{\gamma}_0 \leq \dot{\gamma}_c \end{cases}$$

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5) Predict the material function

$$\underline{\underline{\tau}} = -M(\dot{\gamma}_0)[\nabla \underline{v} + (\nabla \underline{v})^T]$$

$$M(\dot{\gamma}_0) = \begin{cases} M_0 & \dot{\gamma}_0 > \dot{\gamma}_c \\ m\dot{\gamma}_0^{n-1} & \dot{\gamma}_0 \geq \dot{\gamma}_c \end{cases}$$

Steady Elongational Flow Material Functions

Imposed Kinematics:

$$\underline{\underline{\epsilon}} \equiv \begin{pmatrix} -\frac{1}{2}\dot{\epsilon}(t)x_1 \\ -\frac{1}{2}\dot{\epsilon}(t)x_2 \\ \dot{\epsilon}(t)x_3 \end{pmatrix}_{1,2,3}$$

$\dot{\epsilon}(t) = \dot{\epsilon}_0 = \text{constant}$

Material Stress Response:

Material Functions:

Elongational Viscosity $\eta_e(\dot{\epsilon}_0) = \frac{\tau_{33} - \tau_{11}}{\dot{\epsilon}_0} = \frac{-(\tau_{33} - \tau_{11})}{\dot{\epsilon}_0}$

Alternative $\eta_e(\dot{\epsilon}_0)$

$\eta_e = ?$

5) Predict the material function

$$\underline{\underline{\tau}} = -M(\dot{\gamma}_0)[\nabla \underline{v} + (\nabla \underline{v})^T]$$

$$M(\dot{\gamma}_0) = \begin{cases} M_0 & \dot{\gamma}_0 > \dot{\gamma}_c \\ m\dot{\gamma}_0^{n-1} & \dot{\gamma}_0 \geq \dot{\gamma}_c \end{cases}$$

Steady Elongational Flow Material Functions

Imposed Kinematics:

$$\underline{\underline{\epsilon}} \equiv \begin{pmatrix} -\frac{1}{2}\dot{\epsilon}(t)x_1 \\ -\frac{1}{2}\dot{\epsilon}(t)x_2 \\ \dot{\epsilon}(t)x_3 \end{pmatrix}_{1,2,3}$$

$\dot{\epsilon}(t) = \dot{\epsilon}_0 = \text{constant}$

Material Stress Response:

Material Functions:

Elongational Viscosity $\eta_e(\dot{\epsilon}_0) = \frac{\tau_{33} - \tau_{11}}{\dot{\epsilon}_0} = \frac{-(\tau_{33} - \tau_{11})}{\dot{\epsilon}_0}$

Alternative $\eta_e(\dot{\epsilon}_0)$


DOESN'T WORK

$\eta_e = ?$

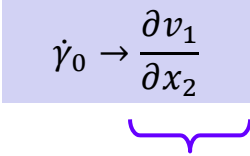
(What is $\dot{\gamma}_0$ doing in an elongational calculation?)

Investigating Stress/Deformation Relationships (Rheology)

1. Choose a material function
2. Predict what Newtonian fluids would do
3. See what non-Newtonian fluids **do**
4. Hypothesize a $\underline{\tau}(\underline{v})$
5. Predict the material function
6. Compare with what non-Newtonian fluids **do**
7. Reflect, **learn**, revise model, repeat.



What if we make the following replacement?



This at least can be written for any flow and it is equal to the shear rate in shear flow.

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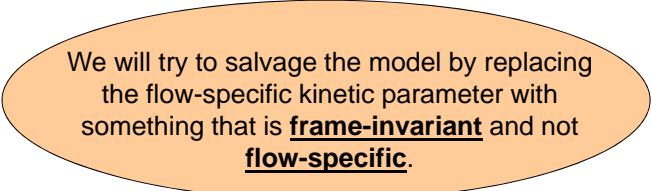
4) Hypothesize a constitutive equation

$$\underline{\tau} = -M(\dot{\gamma}_0)[\nabla \underline{v} + (\nabla \underline{v})^T]$$

Observations

$$M(\dot{\gamma}_0) = \begin{cases} M_0 & \dot{\gamma}_0 > \dot{\gamma}_c \\ m\dot{\gamma}_0^{n-1} & \dot{\gamma}_0 \geq \dot{\gamma}_c \end{cases}$$

- The model contains parameters that are specific to shear flow – makes it impossible to adapt for elongational or mixed flows
- Also, the model should only contain quantities that are independent of coordinate system (i.e. **invariant**)



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4) Hypothesize a constitutive equation

We will take out the shear rate $\dot{\gamma}_0$ and replace with the magnitude of the rate-of-deformation tensor $|\underline{\dot{\gamma}}|$ (which is related to the second invariant of that tensor).

$$\underline{\tau} = -M(|\underline{\dot{\gamma}}|) [\nabla \underline{v} + (\nabla \underline{v})^T]$$

$$M(|\underline{\dot{\gamma}}|) = \begin{cases} M_0 & |\underline{\dot{\gamma}}| > \dot{\gamma}_c \\ m |\underline{\dot{\gamma}}|^{n-1} & |\underline{\dot{\gamma}}| \geq \dot{\gamma}_c \end{cases}$$

(Hold that thought; finish the chapter)

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1) Choose a material function – elongational flow

1. Choose a material function
2. Predict what Newtonian fluids would do
3. See what non-Newtonian fluids **do**
4. Hypothesize a $\underline{\tau}(\underline{v})$
5. Predict the material function
6. Compare with what non-Newtonian fluids **do**
7. Reflect, **learn**, revise model, repeat.

The other elongational experiments are analogous to shear experiments (see text)

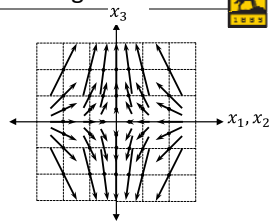
- Elongational stress growth
- Elongational stress cessation (nearly impossible)
- Elongational creep
- Step elongational strain
- Small-amplitude Oscillatory Elongation (SAOE) (Redundant with SAOS)

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Part II-A. Continuum versus molecular modeling  Michigan Tech

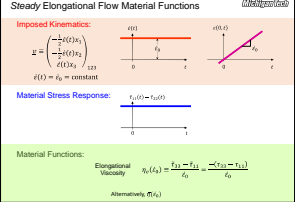
Elongation Material Functions

$$\underline{v} \equiv \begin{pmatrix} -\frac{1}{2}\dot{\epsilon}(t)x_1 \\ -\frac{1}{2}\dot{\epsilon}(t)x_2 \\ \dot{\epsilon}(t)x_3 \end{pmatrix}_{123}$$

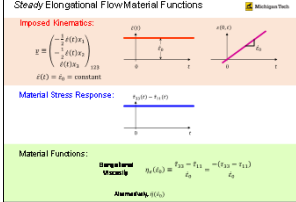


"Recipe cards"

a) Steady



b) Start-up



(currently unobservable)

d) Step strain

(exists, but less often discussed)


e) SAOE

(exists, but easily converted to SAOS so is redundant)

f) Creep

(exists)

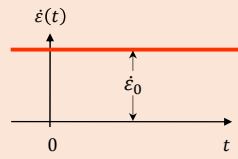
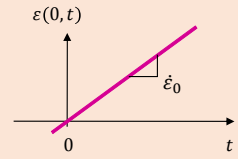
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Steady Elongational Flow Material Functions  Michigan Tech

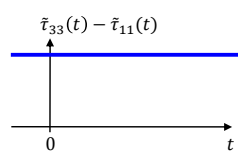
Imposed Kinematics:

$$\underline{v} \equiv \begin{pmatrix} -\frac{1}{2}\dot{\epsilon}(t)x_1 \\ -\frac{1}{2}\dot{\epsilon}(t)x_2 \\ \dot{\epsilon}(t)x_3 \end{pmatrix}_{123}$$

$\dot{\epsilon}(t) = \dot{\epsilon}_0 = \text{constant}$

Material Stress Response:



Material Functions:

Elongational Viscosity $\eta_e(\dot{\epsilon}_0) \equiv \frac{\bar{\tau}_{33} - \bar{\tau}_{11}}{\dot{\epsilon}_0} = \frac{-(\tau_{33} - \tau_{11})}{\dot{\epsilon}_0}$

Alternatively, $\bar{\eta}(\dot{\epsilon}_0)$

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3) See what non-Newtonian fluids do

1. Choose a material function
2. Predict what Newtonian fluids would do
3. See what non-Newtonian fluids **do**
4. Hypothesize a $\underline{\tau}(\underline{\gamma})$
5. Predict the material function
6. Compare with what non-Newtonian fluids **do**
7. Reflect, **learn**, revise model, repeat.

3) See what non-Newtonian fluids **do**

Steady Elongational Flow Material Functions Michigan Tech

Imposed Kinematics:

$$\underline{v} = \begin{pmatrix} -\frac{1}{2}\dot{\epsilon}(t)x_1 \\ -\frac{1}{2}\dot{\epsilon}(t)x_2 \\ \dot{\epsilon}(t)x_3 \end{pmatrix}$$

$\dot{\epsilon}(t) = \dot{\epsilon}_0 = \text{constant}$

Material Stress Response:

$$\tau_{33}(t) - \tau_{11}(t)$$

Material Functions:

Elongational Viscosity $\eta_e(\dot{\epsilon}_0) = \frac{\tau_{33} - \tau_{11}}{\dot{\epsilon}_0} = -\frac{(\tau_{33} - \tau_{11})}{\dot{\epsilon}_0}$

Alternatively, $\hat{\eta}(\dot{\epsilon}_0)$

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3) See what non-Newtonian fluids do

Start-up of Steady Elongation

Strain-hardening

Figure 6.64, p. 218
Kurzbeck et al.; PP

Fit to an advanced constitutive equation (12 mode pom-pom model)

Figure 6.63, p. 217
Inkson et al.; LDPE

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7) Reflect, learn, revise model, repeat

What now?

To proceed to better-designed constitutive equations, we need to know more about material behavior, i.e. we need more material functions to predict, and we need measurements of these material functions.

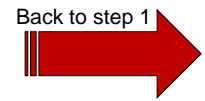
- More non-steady material functions (material functions that tell us about memory)
- Material functions that tell us about nonlinearity (strain)
- Material functions for a different flow

What are material functions and why do we need them?

- We do not know the stress/deformation relationship $\tau(\dot{\gamma})$
- We approach stress/deformation investigations from two directions (**modeling**, **measuring**) to reveal the physics;
- Material functions organize comparisons

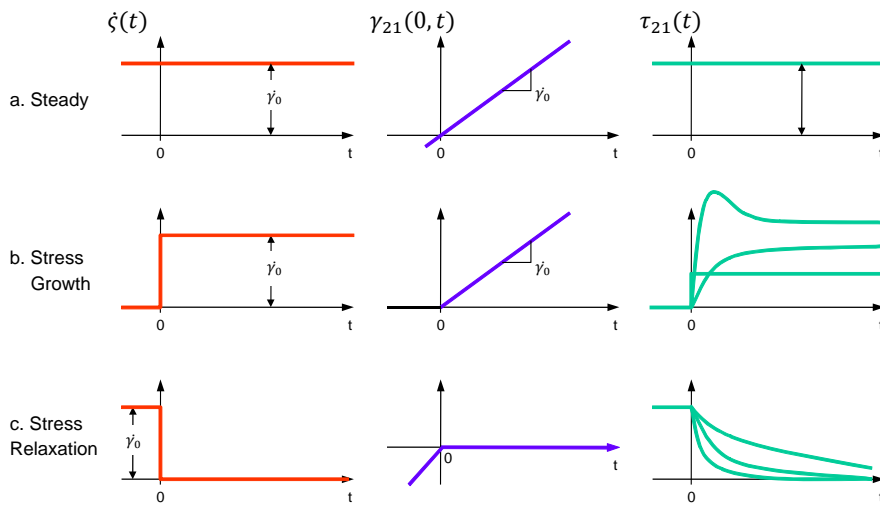
For non-Newtonian fluids:

(7) (4) (2)
 (5) (1)
 (6) (3)



1) Choose a material function – Rate based

Summary of shear rate kinematics (part 1)



1) Choose a material function – Rate based

Summary of shear rate kinematics (part 1, rate-based)

Strain-rate based

a. Steady

b. Stress Growth

c. Stress Relaxation

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1) Choose a material function

7) Reflect, learn, revise model, repeat

To proceed to better-designed constitutive equations, we need to know more about material behavior, i.e. we need more material functions to predict, and we need measurements of these material functions.

- More non-steady material functions (material functions that tell us about memory)
- Material functions that tell us about nonlinearity (strain)

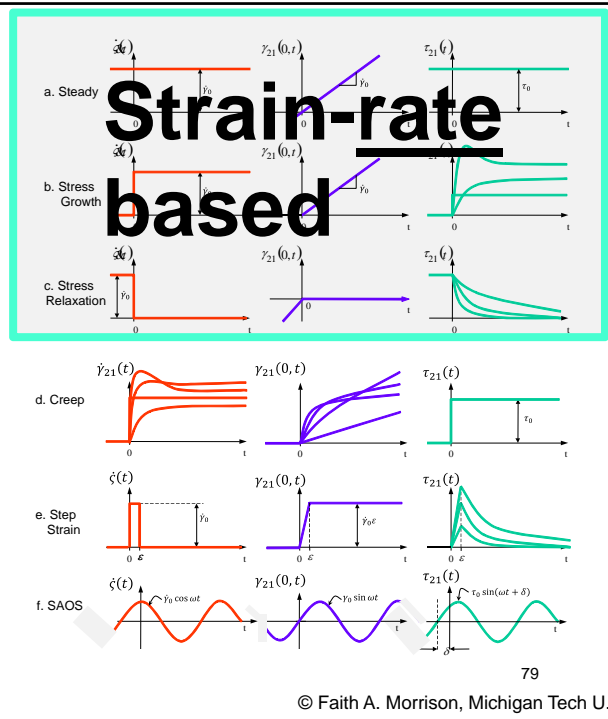
Back to step 1

The next three families of material functions incorporate the concept of **strain**.

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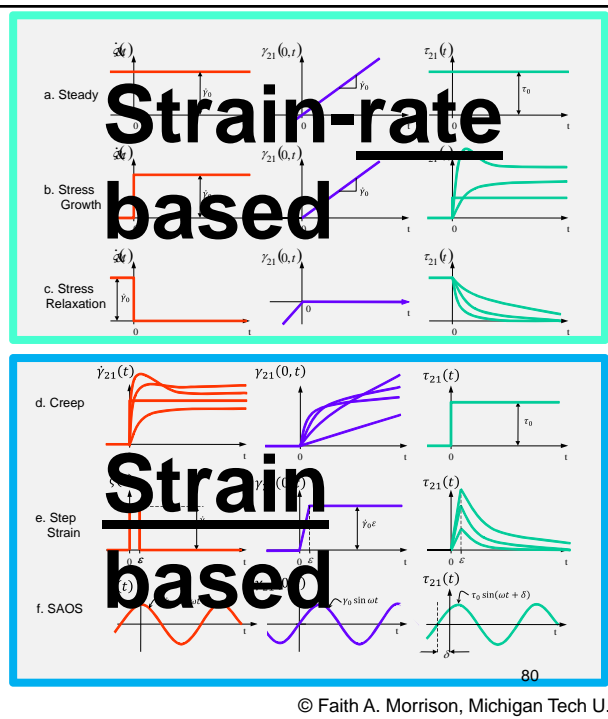
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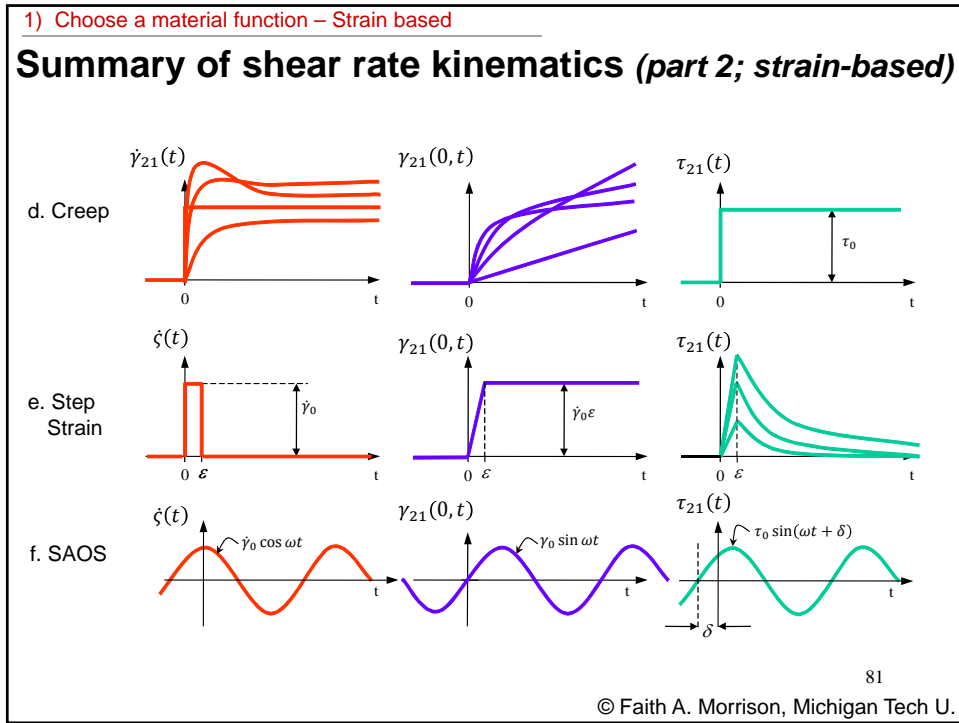
The first three recipe cards were strain-rate based.



The first three recipe cards were strain-rate based.

The second three recipe cards are strain based.





Investigating **Stress/Deformation Relationships (Rheology)**

1) Choose a material function – Strain based

What is **strain**?

Strain is a measure of *deformation* (change in shape)

Initial or reference state

Final state

(shape change relative to some other state)

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What is **strain**? Answer: change in shape

Deformation (=strain)

We need a way to quantify "change in shape" due to flow.

There must be an initial (reference) shape and a final shape (at time of interest)

fluid particle shape at t_{ref}

shape at t

The problem of *change in shape* is a difficult, 3-dimensional problem; we can **start simple** with unidirectional flow (shear).

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What is **strain**? Answer: change in shape

Deformation (=Strain)

We need a way to quantify "change in shape" due to flow.

There must be an initial (reference) shape and a final shape (at time of interest)

fluid particle shape at t_{ref}

shape at t

The problem of *change in shape* is a difficult, 3-dimensional problem; we can **start simple** with unidirectional flow (shear).

NOTE:
Strain can be conceptually complicated

Let's begin with the answer

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What is shear strain? Summary

Strain is our measure of deformation (change of shape)

For shear flow (steady or unsteady, $\dot{\gamma}_{21}(t) = \zeta$):

$\gamma_{21}(t_1, t_2) = \int_{t_1}^{t_2} \dot{\zeta}(t') dt'$	Strain is the integral of strain rate	<i>Strain accumulates as the flow progresses</i>
$\frac{d\gamma_{21}}{dt} = \dot{\gamma}_{21}(t)$ <p style="text-align: center;">Deformation rate</p>	The time derivative of strain is the strain rate	<i>The strain rate is the rate of instantaneous shape change</i>

Shear strain tensor: $\underline{\underline{d\dot{\gamma}}} = \underline{\underline{\frac{d(\dot{\gamma})}{dt}}}$
(see next page)

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Strain Tensor—small strains

Strain is our measure of deformation (change of shape)

Infinitesimal strain tensor: $\underline{\underline{\frac{d\dot{\gamma}}{dt}}} = \underline{\underline{\frac{d(\dot{\gamma})}{dt}}}$

More on this later.

$$\underline{\underline{\gamma}}(t_1, t_2) = \begin{pmatrix} \int_{t_1}^{t_2} \dot{\gamma}_{11}(t') dt' & \int_{t_1}^{t_2} \dot{\gamma}_{12}(t') dt' & \int_{t_1}^{t_2} \dot{\gamma}_{13}(t') dt' \\ \int_{t_1}^{t_2} \dot{\gamma}_{21}(t') dt' & \int_{t_1}^{t_2} \dot{\gamma}_{22}(t') dt' & \int_{t_1}^{t_2} \dot{\gamma}_{23}(t') dt' \\ \int_{t_1}^{t_2} \dot{\gamma}_{31}(t') dt' & \int_{t_1}^{t_2} \dot{\gamma}_{32}(t') dt' & \int_{t_1}^{t_2} \dot{\gamma}_{33}(t') dt' \end{pmatrix}_{123}$$

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What is elongational strain? Summary

Strain is our measure of deformation (change of shape)

For uniaxial elongational flow (steady or unsteady, $\dot{\epsilon}(t)$):

$\epsilon(t_{ref}, t) = \int_{t_{ref}}^t \dot{\epsilon}(t') dt'$	Strain is the integral of strain rate	<i>Strain accumulates as the flow progresses</i>
$\frac{d\epsilon}{dt} = \dot{\epsilon}(t)$ Deformation rate	The time derivative of strain is the strain rate	<i>The strain rate is the rate of instantaneous shape change</i>

(finite-strain tensor is complicated) $\frac{d\underline{\dot{\gamma}}}{dt} = \frac{d\underline{\dot{\epsilon}}}{dt}$ (see Ch9)

Now we can continue with material functions based on strain.

➔

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Practice with strain

□ What is the strain in start-up of steady shear?
(let $t_{ref} = -\infty$)

Start-up of Steady Shear Flow Material Functions @FaithAM

Imposed Kinematics:

$\underline{\dot{\epsilon}} = \begin{pmatrix} \dot{\gamma}(t) & & \\ & 0 & \\ & & 0 \end{pmatrix}$

$\dot{\gamma}(t) = \begin{cases} 0 & t < 0 \\ \dot{\gamma}_0 & t \geq 0 \end{cases}$

Material Stress Response:

Material Functions:

Shear stress growth function $\Psi^*_1(t, \dot{\gamma}_0) = \frac{\tau_{xy}(t)}{\dot{\gamma}_0}$ First normal stress growth coefficient $\Psi^{*1}_1(t, \dot{\gamma}_0) = \frac{\tau_{xx}(t)}{\dot{\gamma}_0^2}$

Second normal stress growth coefficient $\Psi^{*2}_1(t, \dot{\gamma}_0) = \frac{\tau_{zz}(t)}{\dot{\gamma}_0^2}$

□ What is the strain in cessation of steady shear?
(let $t_{ref} = 0$)

Cessation of Steady Shear Flow Material Functions @FaithAM

Imposed Kinematics:

$\underline{\dot{\epsilon}} = \begin{pmatrix} \dot{\gamma}(t) & & \\ & 0 & \\ & & 0 \end{pmatrix}$

$\dot{\gamma}(t) = \begin{cases} \dot{\gamma}_0 & t < 0 \\ 0 & t \geq 0 \end{cases}$

Material Stress Response:

Material Functions:

Shear stress decay function $\Psi^*_1(t, \dot{\gamma}_0) = \frac{\tau_{xy}(t)}{\dot{\gamma}_0}$ First normal stress decay coefficient $\Psi^{*1}_1(t, \dot{\gamma}_0) = \frac{\tau_{xx}(t)}{\dot{\gamma}_0^2}$

Second normal stress decay coefficient $\Psi^{*2}_1(t, \dot{\gamma}_0) = \frac{\tau_{zz}(t)}{\dot{\gamma}_0^2}$

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Start-up of Steady Shear Flow Material Functions

Imposed Kinematics:

$$\underline{v} \equiv \begin{pmatrix} \dot{\zeta}(t)x_2 \\ 0 \\ 0 \end{pmatrix}_{123}$$

$$\dot{\zeta}(t) = \begin{cases} 0 & t \leq 0 \\ \dot{\gamma}_0 & t > 0 \end{cases}$$

Material Stress Response:

Material Functions:

Shear stress growth function $\eta^+(t, \dot{\gamma}_0) \equiv \frac{\bar{\tau}_{21}(t)}{\dot{\gamma}_0} = \frac{-\tau_{21}(t)}{\dot{\gamma}_0}$

First normal-stress growth coefficient $\Psi_1^+(t, \dot{\gamma}_0) \equiv \frac{\bar{\tau}_{11} - \bar{\tau}_{22}}{\dot{\gamma}_0^2}$

Second normal-stress growth coefficient $\Psi_2^+(t, \dot{\gamma}_0) \equiv \frac{\bar{\tau}_{22} - \bar{\tau}_{33}}{\dot{\gamma}_0^2}$

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Cessation of Steady Shear Flow Material Functions

Imposed Kinematics:

$$\underline{v} \equiv \begin{pmatrix} \dot{\zeta}(t)x_2 \\ 0 \\ 0 \end{pmatrix}_{123}$$

$$\dot{\zeta}(t) = \begin{cases} \dot{\gamma}_0 & t < 0 \\ 0 & t \geq 0 \end{cases}$$

Material Stress Response:

Material Functions:

Shear stress decay function $\eta^-(t, \dot{\gamma}_0) \equiv \frac{\bar{\tau}_{21}(t)}{\dot{\gamma}_0} = \frac{-\tau_{21}(t)}{\dot{\gamma}_0}$

First normal-stress decay coefficient $\Psi_1^-(t, \dot{\gamma}_0) \equiv \frac{\bar{\tau}_{11} - \bar{\tau}_{22}}{\dot{\gamma}_0^2}$

Second normal-stress decay coefficient $\Psi_2^-(t, \dot{\gamma}_0) \equiv \frac{\bar{\tau}_{22} - \bar{\tau}_{33}}{\dot{\gamma}_0^2}$

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1) Choose a material function – Strain based

Summary of shear rate kinematics (part 2; strain-based)

d. Creep

e. Step Strain

f. SAOS

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Step Strain Shear Flow Material Functions

Imposed Kinematics:

$$\underline{v} \equiv \begin{pmatrix} \dot{\zeta}(t)x_2 \\ 0 \\ 0 \end{pmatrix}_{123}$$

$$\dot{\zeta}(t) = \lim_{\varepsilon \rightarrow 0} \begin{cases} 0 & t \leq 0 \\ \gamma_0/\varepsilon & 0 < t < \varepsilon \\ 0 & t \geq \varepsilon \end{cases}$$

Material Stress Response:

Material Functions:

Relaxation modulus $G(t, \gamma_0) \equiv \frac{\bar{\tau}_{21}(t, \gamma_0)}{\gamma_0} = \frac{-\tau_{21}(t, \gamma_0)}{\gamma_0}$

First normal-stress relaxation modulus $G_{\Psi_1}(t, \gamma_0) \equiv \frac{\bar{\tau}_{11} - \bar{\tau}_{22}}{\gamma_0^2}$

Second normal-stress relaxation modulus $G_{\Psi_2}(t, \gamma_0) \equiv \frac{\bar{\tau}_{22} - \bar{\tau}_{33}}{\gamma_0^2}$

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1) Choose a material function – Strain based

What is the **strain** in the step-strain flow?

?

You try.

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1) Choose a material function – Strain based

What is the **strain** in the step-strain flow?

$$\begin{aligned} \gamma_{21}(-\infty, t) &= \int_{-\infty}^t \dot{\gamma}(t') dt' \\ &= \int_{-\infty}^t \lim_{\varepsilon \rightarrow 0} \left(\begin{cases} 0 & t' < 0 \\ \gamma_0/\varepsilon & 0 \leq t' < \varepsilon \\ 0 & t \geq \varepsilon \end{cases} \right) dt' \\ &= \lim_{\varepsilon \rightarrow 0} \int_0^\varepsilon \frac{\gamma_0}{\varepsilon} dt' \\ &= \gamma_0 \end{aligned}$$

The strain imposed is a constant

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2) Predict what Newtonian fluids would do.

1. Choose a material function
2. Predict what Newtonian fluids would do
3. See what non-Newtonian fluids **do**
4. Hypothesize a $\underline{\tau}(\underline{\gamma})$
5. Predict the material function
6. Compare with what non-Newtonian fluids **do**
7. Reflect, **learn**, revise model, repeat.

2) Predict what Newtonian fluids would do.

?

Step Strain Shear Flow Material Functions Michigan Tech

Imposed Kinematics:

$$\underline{\gamma} = \begin{pmatrix} \langle \dot{\gamma}(t) \rangle & 0 \\ 0 & 0 \\ 0 & 0 \end{pmatrix}$$

$$\langle \dot{\gamma}(t) \rangle = \lim_{\epsilon \rightarrow 0} \begin{cases} \gamma_0/\epsilon & 0 < t < \epsilon \\ 0 & t \geq \epsilon \end{cases}$$

Material Stress Response:

Material Functions:

Relaxation modulus $G(t, \gamma_0) \equiv \frac{\tau_{11}(t, \gamma_0)}{\gamma_0} = -\frac{\tau_{21}(t, \gamma_0)}{\gamma_0}$

First normal-stress relaxation modulus $G_{\Psi_1}(t, \gamma_0) \equiv \frac{\tau_{11} - \tau_{22}}{\gamma_0^2}$

Second normal-stress relaxation modulus $G_{\Psi_2}(t, \gamma_0) \equiv \frac{\tau_{22} - \tau_{33}}{\gamma_0^2}$

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2) Predict what Newtonian fluids would do.

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6. Compare with what non-Newtonian fluids **do**
7. Reflect, **learn**, revise model, repeat.

2) Predict what Newtonian fluids would do.

You try.

Step Strain Shear Flow Material Functions Michigan Tech

Imposed Kinematics:

$$\underline{\gamma} = \begin{pmatrix} \langle \dot{\gamma}(t) \rangle & 0 \\ 0 & 0 \\ 0 & 0 \end{pmatrix}$$

$$\langle \dot{\gamma}(t) \rangle = \lim_{\epsilon \rightarrow 0} \begin{cases} \gamma_0/\epsilon & 0 < t < \epsilon \\ 0 & t \geq \epsilon \end{cases}$$

Material Stress Response:

Material Functions:

Relaxation modulus $G(t, \gamma_0) \equiv \frac{\tau_{11}(t, \gamma_0)}{\gamma_0} = -\frac{\tau_{21}(t, \gamma_0)}{\gamma_0}$

First normal-stress relaxation modulus $G_{\Psi_1}(t, \gamma_0) \equiv \frac{\tau_{11} - \tau_{22}}{\gamma_0^2}$

Second normal-stress relaxation modulus $G_{\Psi_2}(t, \gamma_0) \equiv \frac{\tau_{22} - \tau_{33}}{\gamma_0^2}$

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2) Predict what Newtonian fluids would do.

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5. Predict the material function
6. Compare with what non-Newtonian fluids **do**
7. Reflect, **learn**, revise model, repeat.

2) Predict what Newtonian fluids would do.

Answer:
mostly
zero

Step Strain Shear Flow Material Functions Michigan Tech

Imposed Kinematics:

$$\underline{\gamma} = \begin{pmatrix} \langle \dot{\gamma}(t) \rangle & 0 \\ 0 & 0 \end{pmatrix} \begin{matrix} 123 \\ 233 \end{matrix}$$

$$\langle \dot{\gamma}(t) \rangle = \lim_{\epsilon \rightarrow 0} \begin{cases} 0 & t \leq 0 \\ \gamma_0/\epsilon & 0 < t < \epsilon \\ 0 & t \geq \epsilon \end{cases}$$

Material Stress Response:

Material Functions:

Relaxation modulus $G(t, \gamma_0) \equiv \frac{\tau_{11}(t, \gamma_0)}{\gamma_0} = -\frac{\tau_{11}(t, \gamma_0)}{\gamma_0}$

First normal-stress relaxation modulus $G_{\Psi_1}(t, \gamma_0) \equiv \frac{\tau_{11} - \tau_{22}}{\gamma_0^2}$

Second normal-stress relaxation modulus $G_{\Psi_2}(t, \gamma_0) \equiv \frac{\tau_{22} - \tau_{33}}{\gamma_0^2}$

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3) See what non-Newtonian fluids do

1. Choose a material function
2. Predict what Newtonian fluids would do
3. See what non-Newtonian fluids **do**
4. Hypothesize a $\underline{\tau}(\underline{\gamma})$
5. Predict the material function
6. Compare with what non-Newtonian fluids **do**
7. Reflect, **learn**, revise model, repeat.

3) See what non-Newtonian fluids **do**

?

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3) See what non-Newtonian fluids do

Step shear strain - strain dependence

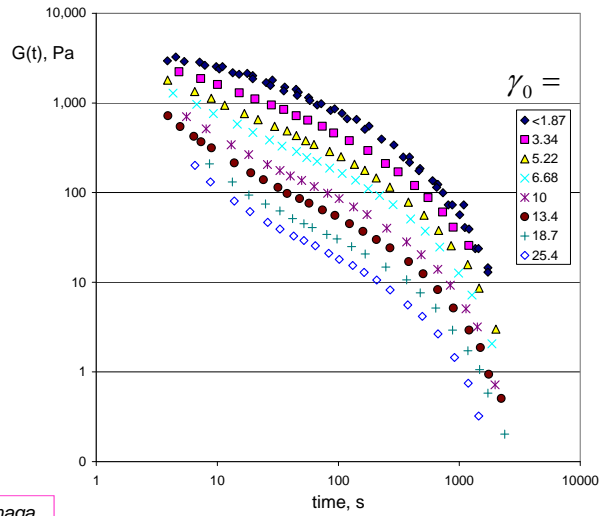


Figure 6.57, p. 212 Einaga et al.; PS soln

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3) See what non-Newtonian fluids do

Linear viscoelastic limit

$$\lim_{\gamma_0 \rightarrow 0} G(t, \gamma_0) = G(t)$$

At small strains the relaxation modulus is independent of strain.

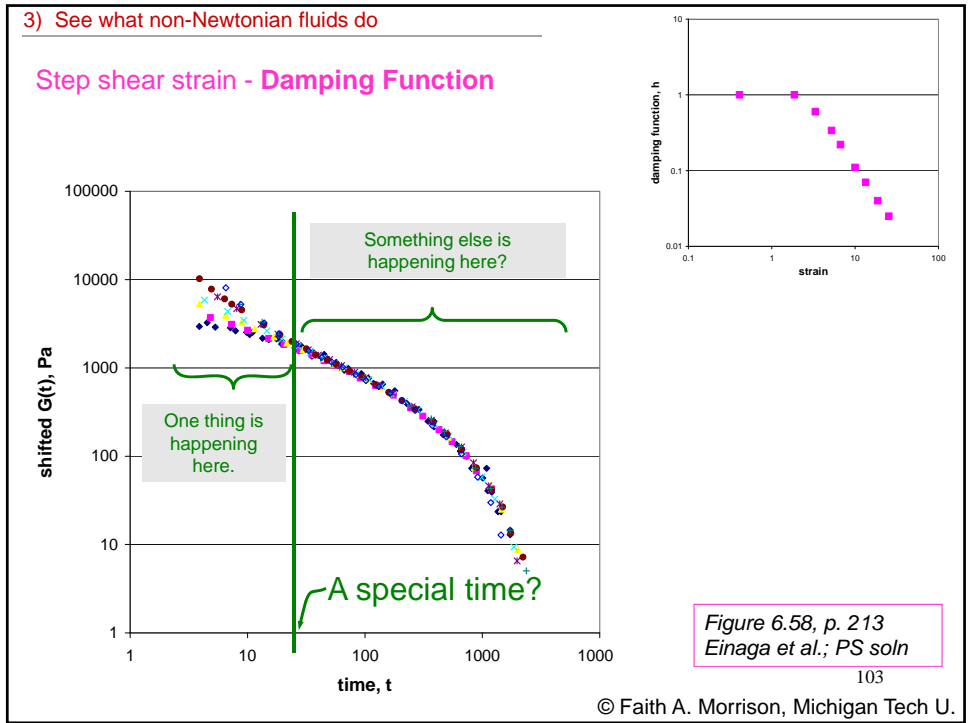
The polystyrene solutions on the previous slide show time-strain independence, i.e. the curves have the same shape at different strains.

Damping function, $h(\gamma_0)$:

$$h(\gamma_0) \equiv \frac{G(t, \gamma_0)}{G(t)}$$

The damping function summarizes the non-linear effects as a function of strain amplitude.

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3) See what non-Newtonian fluids do

What types of materials generate stress in proportion to the strain imposed? Answer: elastic solids

Hooke's Law for elastic solids: $\tau_{21}(t) = -G\gamma_{21}(0, t)$
(shear flow)

initial state,
no flow,
no forces

deformed state,
 $\tau_{21} = -G \frac{\Delta u_1}{\Delta x_2}$

Hooke's law for elastic solids

initial state,
no force

deformed state,
 $f_1 = -k\Delta x_1$

spring restoring force

Hooke's law for linear springs

Similar to the linear spring law

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2) Predict what Newtonian fluids would do.

1. Choose a material function
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5. Predict the material function
6. Compare with what non-Newtonian fluids **do**
7. Reflect, **learn**, revise model, repeat.

Hookean solids

2) Predict what ~~Newtonian fluids~~ would do.

Hookean Solid
Constitutive
Equation

$$\underline{\tau} = -G\underline{\gamma}(0, t)$$

?

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2) Predict what Newtonian fluids would do.

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5. Predict the material function
6. Compare with what non-Newtonian fluids **do**
7. Reflect, **learn**, revise model, repeat.

Hookean solids

2) Predict what ~~Newtonian fluids~~ would do.

Hookean Solid
Constitutive
Equation

$$\underline{\tau} = -G\underline{\gamma}(0, t)$$

Answer: much more interesting.

Solution:

- Recipe card gives kinematics
- Calculate $\underline{\gamma}(t)$
- Calculate material functions

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Investigating Stress/Deformation Relationships (Rheology)

1. Choose a material function
2. Predict what Newtonian fluids would do
3. See what non-Newtonian fluids **do**
4. Hypothesize a $\underline{\tau}(\underline{\gamma})$
5. Predict the material function
6. Compare with what non-Newtonian fluids **do**
7. Reflect, **learn**, revise model, repeat.

1) Choose a material function

Kinematics

{

1. Choice of flow (shear or elongation)

$$\underline{v} = \begin{pmatrix} \dot{\zeta}(t)x_2 \\ 0 \\ 0 \end{pmatrix}_{123}$$

$$\underline{v} = \begin{pmatrix} -\frac{1}{2}\dot{\epsilon}(t)x_1 \\ -\frac{1}{2}\dot{\epsilon}(t)x_2 \\ \dot{\epsilon}(t)x_3 \end{pmatrix}_{123}$$

2. Choice of time dependence of $\zeta(t)$ or $\dot{\epsilon}(t)$

3. Material functions definitions: will be based on τ_{21} , N_1 , N_2 in shear or $\tau_{22} - \tau_{11}$, $\tau_{22} - \tau_{11}$ in elongational flows.

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1) Choose a material function – Strain based

Summary of shear rate kinematics (part 2; strain-based)

d. Creep

The first graph shows shear rate $\dot{\gamma}_{21}(t)$ vs time t with multiple curves that rise and then level off. The second graph shows strain $\gamma_{21}(0, t)$ vs time t with multiple curves that rise and then level off. The third graph shows stress $\tau_{21}(t)$ vs time t with a single step function that jumps to a constant value τ_0 at $t=0$.


e. Step Strain

The first graph shows shear rate $\dot{\zeta}(t)$ vs time t with a single rectangular pulse of height $\dot{\gamma}_0$ from $t=0$ to $t=\epsilon$. The second graph shows strain $\gamma_{21}(0, t)$ vs time t with a single step function that jumps to a constant value $\dot{\gamma}_0\epsilon$ at $t=\epsilon$. The third graph shows stress $\tau_{21}(t)$ vs time t with multiple curves that rise to a peak at $t=\epsilon$ and then decay.

f. SAOS

The first graph shows shear rate $\dot{\zeta}(t)$ vs time t with a sinusoidal wave $\dot{\gamma}_0 \cos \omega t$. The second graph shows strain $\gamma_{21}(0, t)$ vs time t with a sinusoidal wave $\dot{\gamma}_0 \sin \omega t$. The third graph shows stress $\tau_{21}(t)$ vs time t with a sinusoidal wave $\tau_0 \sin(\omega t + \delta)$ that is phase-shifted by δ relative to the strain.

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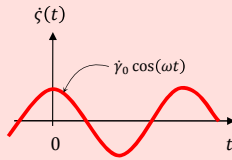
Small-Amplitude Oscillatory Shear Material Functions

Imposed Kinematics:

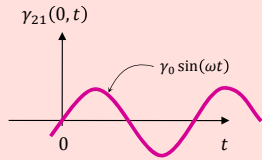
$$\underline{v} \equiv \begin{pmatrix} \dot{\zeta}(t)x_2 \\ 0 \\ 0 \end{pmatrix}_{123}$$

$$\dot{\zeta}(t) = \dot{\gamma}_0 \cos(\omega t)$$

$$\gamma_0 = \frac{\dot{\gamma}_0}{\omega}$$



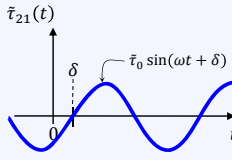
$\zeta(t)$
 $\gamma_0 \cos(\omega t)$



$\gamma_{21}(0,t)$
 $\gamma_0 \sin(\omega t)$

Material Stress Response:

$\delta = \text{phase difference between stress and strain waves}$



$\tau_{21}(t)$
 $\tau_0 \sin(\omega t + \delta)$

$N_1(t) = N_2(t) = 0$
(linear viscoelastic regime)

Material Functions:

SAOS stress $\frac{\tilde{\tau}_{21}(t, \gamma_0)}{\gamma_0} = \frac{-\tau_{21}(t, \gamma_0)}{\gamma_0} = \tilde{\tau}_0 \sin(\omega t + \delta) = G' \sin(\omega t) + G'' \cos(\omega t)$

Storage modulus $G'(\omega) \equiv \frac{\tilde{\tau}_0}{\gamma_0} \cos(\delta)$

Loss modulus $G''(\omega) \equiv \frac{\tilde{\tau}_0}{\gamma_0} \sin(\delta)$

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1) Choose a material function – Strain based _____

What is the strain in small-amplitude oscillatory shear?
(let $t_{ref} = 0$)

Answer: $\gamma_{21}(0, t) = \frac{\dot{\gamma}_0}{\omega} \sin \omega t$

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1) Choose a material function – Strain based

In **SAOS** the strain amplitude is small, and a sinusoidal imposed strain induces a sinusoidal measured stress.

$$-\tau_{21}(t) = \tau_0 \sin(\omega t + \delta)$$

$$\begin{aligned} -\tau_{21}(t) &= \tau_0 \sin(\omega t + \delta) \\ &= \tau_0 \sin \omega t \cos \delta + \tau_0 \cos \omega t \sin \delta \\ &= [\tau_0 \cos \delta] \sin \omega t + [\tau_0 \sin \delta] \cos \omega t \end{aligned}$$

portion in-phase with strain

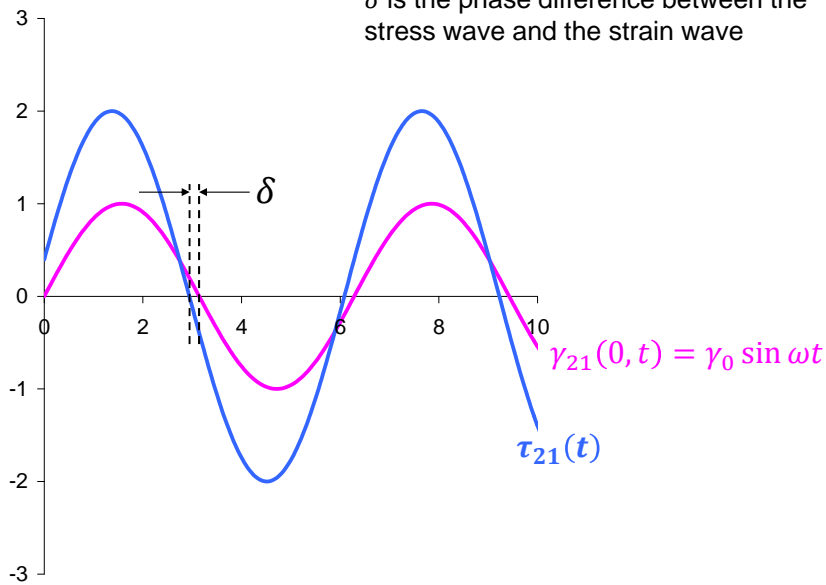
portion in-phase with strain-rate

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1) Choose a material function – Strain based

δ is the phase difference between the stress wave and the strain wave



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1) Choose a material function – Strain based

SAOS Material Functions

$$\frac{-\tau_{21}(t)}{\gamma_0} = \left[\frac{\tau_0 \cos \delta}{\gamma_0} \right] \sin \omega t + \left[\frac{\tau_0 \sin \delta}{\gamma_0} \right] \cos \omega t$$

portion in-phase with strain

G'

portion in-phase with strain-rate

G''

For Newtonian fluids, stress is proportional to strain rate: $\tau_{21} = -\mu \dot{\gamma}_{21}$

G'' is thus known as the viscous loss modulus. It characterizes the viscous contribution to the stress response.

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1) Choose a material function – Strain based

SAOS Material Functions

$$\frac{-\tau_{21}(t)}{\gamma_0} = \left[\frac{\tau_0 \cos \delta}{\gamma_0} \right] \sin \omega t + \left[\frac{\tau_0 \sin \delta}{\gamma_0} \right] \cos \omega t$$

portion in-phase with strain

G'

portion in-phase with strain-rate

G''

$\tau_{21} = -G\gamma_{21}$

For Hookean solids, stress is proportional to strain :

G' is thus known as the elastic storage modulus. It characterizes the elastic contribution to the stress response.

(note: SAOS material functions may also be expressed in complex notation. See pp. 156-159 of Morrison, 2001)

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2) Predict what Newtonian fluids would do.

1. Choose a material function
2. Predict what Newtonian fluids would do
3. See what non-Newtonian fluids **do**
4. Hypothesize a $\underline{\tau}(\underline{\gamma})$
5. Predict the material function
6. Compare with what non-Newtonian fluids **do**
7. Reflect, **learn**, revise model, repeat.

2) Predict what Newtonian fluids would do.

?

Small-Amplitude Oscillatory Shear Material Functions Mechanisms

Imposed Kinematics:

$$\underline{\underline{\epsilon}} \equiv \begin{pmatrix} \epsilon(t) & \kappa_2 \\ 0 & 123 \end{pmatrix}$$

$$\epsilon(t) = \gamma_0 \cos(\omega t)$$

$$\gamma_0 = \frac{\tau_0}{\omega}$$

Material Stress Response:

$$\tau_{21}(t) = \tau_0 \sin(\omega t + \delta)$$

δ = phase difference between stress and strain waves

$N_1(t) = N_2(t) = 0$ (linear viscoelastic regime)

Material Functions:

SAOS stress $\frac{\tau_{21}(t, \kappa_2)}{\gamma_0} = \frac{-\tau_{21}(t, \dot{\gamma})}{\gamma_0} = \tau_0 \sin(\omega t + \delta) = G' \sin(\omega t) + G'' \cos(\omega t)$

Storage modulus $G'(\omega) \equiv \frac{\tau_0}{\gamma_0} \cos(\delta)$ Loss modulus $G''(\omega) \equiv \frac{\tau_0}{\gamma_0} \sin(\delta)$

Answer: $\delta = \frac{\pi}{2}; G'' = \mu\omega$

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2) Predict what Newtonian fluids would do.

1. Choose a material function
2. Predict what Newtonian fluids would do
3. See what non-Newtonian fluids **do**
4. Hypothesize a $\underline{\tau}(\underline{\gamma})$
5. Predict the material function
6. Compare with what non-Newtonian fluids **do**
7. Reflect, **learn**, revise model, repeat.

Hookean solids

2) Predict what ~~Newtonian fluids~~ would do.

Hookean Solid Constitutive Equation

$$\underline{\underline{\tau}} = -G\underline{\underline{\gamma}}(0, t)$$

?

Small-Amplitude Oscillatory Shear Material Functions Mechanisms

Imposed Kinematics:

$$\underline{\underline{\epsilon}} \equiv \begin{pmatrix} \epsilon(t) & \kappa_2 \\ 0 & 123 \end{pmatrix}$$

$$\epsilon(t) = \gamma_0 \cos(\omega t)$$

$$\gamma_0 = \frac{\tau_0}{\omega}$$

Material Stress Response:

$$\tau_{21}(t) = \tau_0 \sin(\omega t + \delta)$$

δ = phase difference between stress and strain waves

$N_1(t) = N_2(t) = 0$ (linear viscoelastic regime)

Material Functions:

SAOS stress $\frac{\tau_{21}(t, \kappa_2)}{\gamma_0} = \frac{-\tau_{21}(t, \dot{\gamma})}{\gamma_0} = \tau_0 \sin(\omega t + \delta) = G' \sin(\omega t) + G'' \cos(\omega t)$

Storage modulus $G'(\omega) \equiv \frac{\tau_0}{\gamma_0} \cos(\delta)$ Loss modulus $G''(\omega) \equiv \frac{\tau_0}{\gamma_0} \sin(\delta)$

Answer: $\delta = 0; G' = G$

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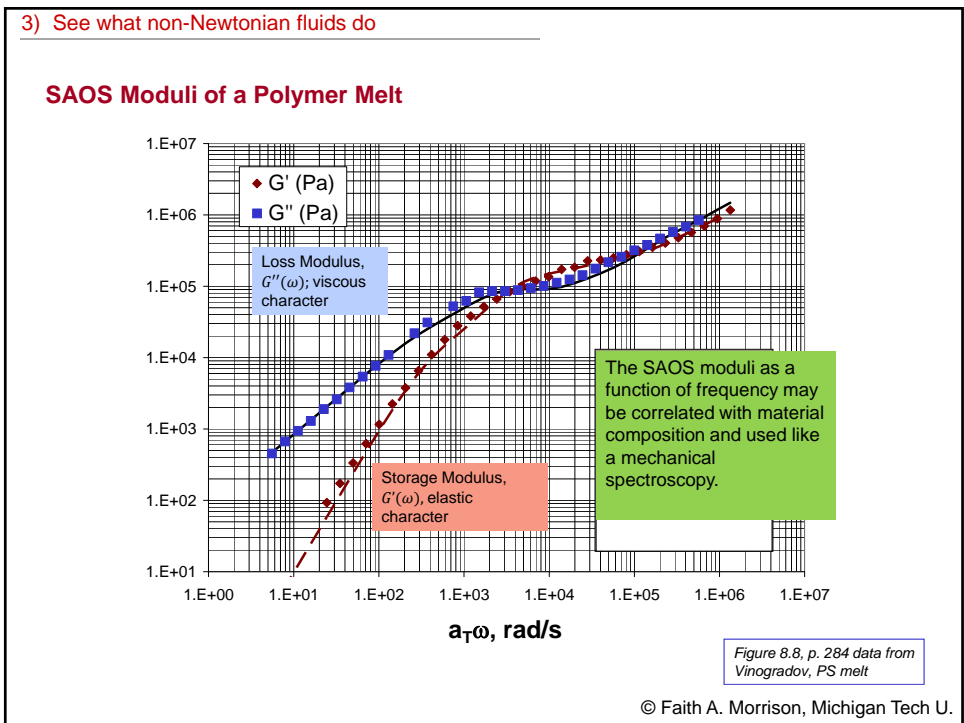
3) See what non-Newtonian fluids do

1. Choose a material function
2. Predict what Newtonian fluids would do
3. See what non-Newtonian fluids **do**
4. Hypothesize a $\underline{\tau}(\underline{v})$
5. Predict the material function
6. Compare with what non-Newtonian fluids **do**
7. Reflect, **learn**, revise model, repeat.

3) See what non-Newtonian fluids **do**

?

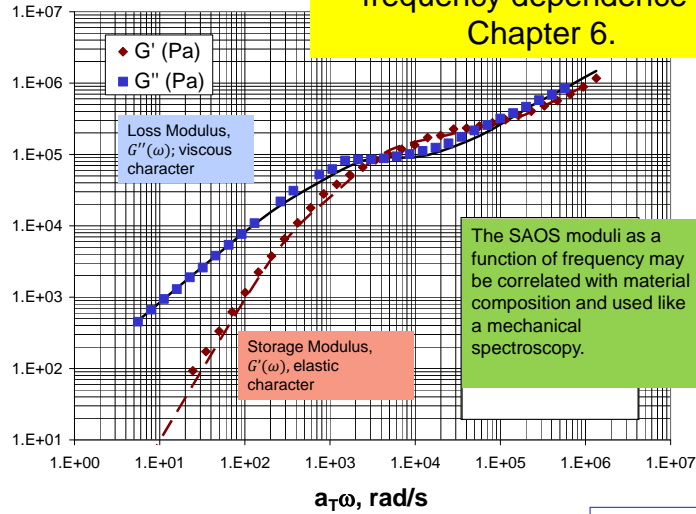
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3) See what non-Newtonian fluids do

SAOS Moduli of a Polymer Melt

We'll talk more about this frequency dependence in Chapter 6.



The SAOS moduli as a function of frequency may be correlated with material composition and used like a mechanical spectroscopy.

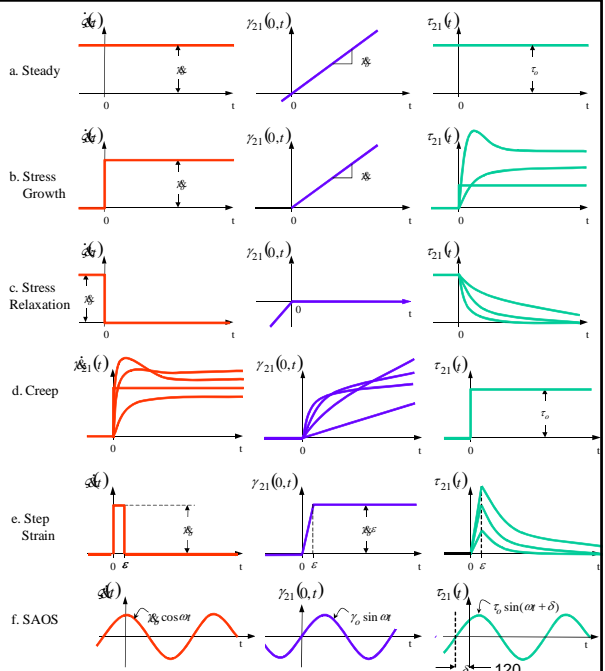
Figure 8.8, p. 284 data from Vinogradov, PS melt

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We have discussed six shear material functions;

Now, the equivalent **elongational** material functions

$$\underline{v} \equiv \begin{pmatrix} -\frac{1}{2} \dot{\epsilon}(t)x_1 \\ -\frac{1}{2} \dot{\epsilon}(t)x_2 \\ \dot{\epsilon}(t)x_3 \end{pmatrix} \quad 123$$



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Steady Elongational Flow Material Functions

Imposed Kinematics:

$$\underline{v} \equiv \begin{pmatrix} -\frac{1}{2}\dot{\epsilon}(t)x_1 \\ -\frac{1}{2}\dot{\epsilon}(t)x_2 \\ \dot{\epsilon}(t)x_3 \end{pmatrix}_{123}$$

$\dot{\epsilon}(t) = \dot{\epsilon}_0 = \text{constant}$

Material Stress Response:

Material Functions:

Elongational Viscosity

$$\eta_e(\dot{\epsilon}_0) \equiv \frac{\bar{\tau}_{33} - \bar{\tau}_{11}}{\dot{\epsilon}_0} = \frac{-(\tau_{33} - \tau_{11})}{\dot{\epsilon}_0}$$

Alternatively, $\bar{\eta}(\dot{\epsilon}_0)$

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1) Choose a material function – elongational flow


1. Choose a material function
2. Predict what Newtonian fluids would do
3. See what non-Newtonian fluids **do**
4. Hypothesize a $\underline{\tau}(\underline{v})$
5. Predict the material function
6. Compare with what non-Newtonian fluids **do**
7. Reflect, **learn**, revise model, repeat.

The other elongational experiments are analogous to shear experiments (see text)

- Elongational stress growth
- Elongational stress cessation (*nearly impossible*)
- Elongational creep
- Step elongational strain
- Small-amplitude Oscillatory Elongation (SAOE)
(Redundant with SAOS)

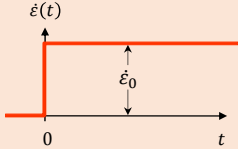
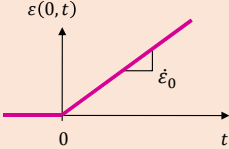
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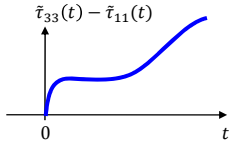
Start-up of Steady Elongation Material Functions 

Imposed Kinematics:

$$\underline{v} \equiv \begin{pmatrix} -\frac{1}{2}\dot{\epsilon}(t)x_1 \\ -\frac{1}{2}\dot{\epsilon}(t)x_2 \\ \dot{\epsilon}(t)x_3 \end{pmatrix}_{123}$$

$$\dot{\epsilon}(t) = \begin{cases} 0 & t < 0 \\ \dot{\epsilon}_0 & t \geq 0 \end{cases}$$



Material Stress Response:



Material Functions:

Elongational Start-up Function

$$\eta_e^+(t, \dot{\epsilon}_0) \equiv \frac{\bar{\tau}_{33} - \bar{\tau}_{11}}{\dot{\epsilon}_0} = \frac{-(\tau_{33} - \tau_{11})}{\dot{\epsilon}_0}$$


Alternatively, $\bar{\eta}^+(t, \dot{\epsilon}_0)$

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3) See what non-Newtonian fluids do

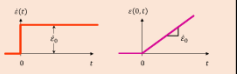

1. Choose a material function
2. Predict what Newtonian fluids would do
3. See what non-Newtonian fluids **do**
4. Hypothesize a $\underline{\tau}(\underline{v})$
5. Predict the material function
6. Compare with what non-Newtonian fluids **do**
7. Reflect, **learn**, revise model, repeat.

3) See what non-Newtonian fluids **do**


Start-up of Steady Elongation Material Functions 

Imposed Kinematics:

$$\underline{v} \equiv \begin{pmatrix} -\frac{1}{2}\dot{\epsilon}(t)x_1 \\ -\frac{1}{2}\dot{\epsilon}(t)x_2 \\ \dot{\epsilon}(t)x_3 \end{pmatrix}_{123}$$

$$\dot{\epsilon}(t) = \begin{cases} 0 & t < 0 \\ \dot{\epsilon}_0 & t \geq 0 \end{cases}$$



Material Stress Response:



Material Functions:

Elongational Start-up Function

$$\eta_e^+(t, \dot{\epsilon}_0) \equiv \frac{\bar{\tau}_{33} - \bar{\tau}_{11}}{\dot{\epsilon}_0} = \frac{-(\tau_{33} - \tau_{11})}{\dot{\epsilon}_0}$$

Alternatively, $\bar{\eta}^+(t, \dot{\epsilon}_0)$

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3) See what non-Newtonian fluids do

Start-up of Steady Elongation

Figure 6.64, p. 218
Kurzbeck et al.; PP

Strain-hardening

Fit to an advanced constitutive equation (12 mode pom-pom model)

Figure 6.63, p. 217
Inkson et al.; LDPE

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Part II-A. Continuum versus molecular modeling

Elongation Material Functions

$$\underline{v} \equiv \begin{pmatrix} -\frac{1}{2}\dot{\epsilon}(t)x_1 \\ -\frac{1}{2}\dot{\epsilon}(t)x_2 \\ \dot{\epsilon}(t)x_3 \end{pmatrix}_{123}$$

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"Recipe cards"

<p>a) Steady</p> <p>Steady Elongational Flow Material Functions</p> <p>Imposed Kinematics: $\underline{\epsilon} = \begin{pmatrix} -\frac{1}{2}\dot{\epsilon}(t)x_1 \\ -\frac{1}{2}\dot{\epsilon}(t)x_2 \\ \dot{\epsilon}(t)x_3 \end{pmatrix}_{123}$, $\dot{\epsilon}(t) = \dot{\epsilon}_0 = \text{constant}$</p> <p>Material Stress Response: $\tau_{ij}(t) = \tau_{ij}(t)$</p> <p>Material Functions: Elongational Viscosity $\eta_E(\dot{\epsilon}_0) = \frac{\tau_{11} - \tau_{22}}{\dot{\epsilon}_0} = -\frac{\tau_{33} - \tau_{11}}{\dot{\epsilon}_0}$, Alternately, $\eta(\dot{\epsilon}_0)$</p>	<p>b) Start-up</p> <p>Steady Elongational Flow Material Functions</p> <p>Imposed Kinematics: $\underline{\epsilon} = \begin{pmatrix} -\frac{1}{2}\dot{\epsilon}(t)x_1 \\ -\frac{1}{2}\dot{\epsilon}(t)x_2 \\ \dot{\epsilon}(t)x_3 \end{pmatrix}_{123}$, $\dot{\epsilon}(t) = \dot{\epsilon}_0 = \text{constant}$</p> <p>Material Stress Response: $\tau_{ij}(t) = \tau_{ij}(t)$</p> <p>Material Functions: Dimensional Viscosity $\eta_E(\dot{\epsilon}_0) = \tau_{11} - \tau_{22} = -(\tau_{33} - \tau_{11})$, $\dot{\epsilon}_0$, Anisotropy $\beta(\dot{\epsilon}_0)$</p>	<p>c) Cessation</p> <p>(currently unobservable)</p>
<p>d) Step strain</p> <p>(exists, but less often discussed)</p>	<p>e) SAOE</p> <p>(exists, but easily converted to SAOS so is redundant)</p>	<p>f) Creep</p> <p>(exists)</p>

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What's next?

Make better constitutive equations

1. Add invariants (replace $\dot{\gamma}_0$, which is flow-specific).
2. Make constitutive equations that reference flow in the past (not purely instantaneous)
3. Investigate strain

Be inspired by material behavior

1. Become informed on more rheological behavior
2. Get more of a feel for what is observed, and when

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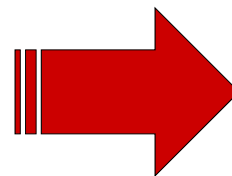
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Done with Material Functions.

The thumbnail slide contains the following content:

- Chapter 5: Material Functions**
- Kinematics:** Steady Shear Flow Material Functions. Velocity profile $v = \begin{pmatrix} \dot{\gamma}y \\ 0 \\ 0 \end{pmatrix}$. Shear rate $\dot{\gamma} = \dot{\gamma}_0 = \text{constant}$.
- Material Functions:**
 - Viscosity: $\eta = \frac{\tau_{xy}}{\dot{\gamma}}$
 - First normal stress coefficient: $\Psi_1 = \frac{\sigma_{11} - \sigma_{22}}{\dot{\gamma}^2}$
 - Second normal stress coefficient: $\Psi_2 = \frac{\sigma_{22} - \sigma_{33}}{\dot{\gamma}^2}$
- © Faith A. Morrison, Michigan Tech U.

Let's move on to Experimental Data

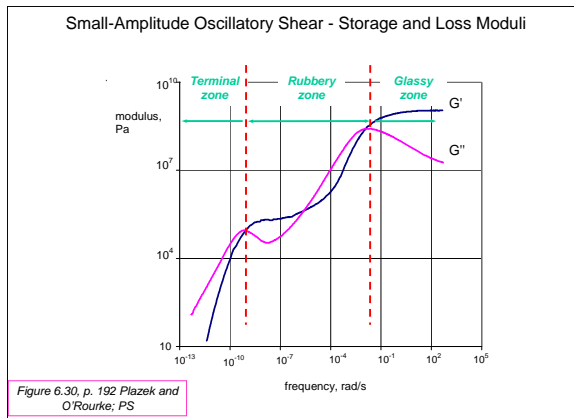


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Chapter 6: Experimental Data

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