

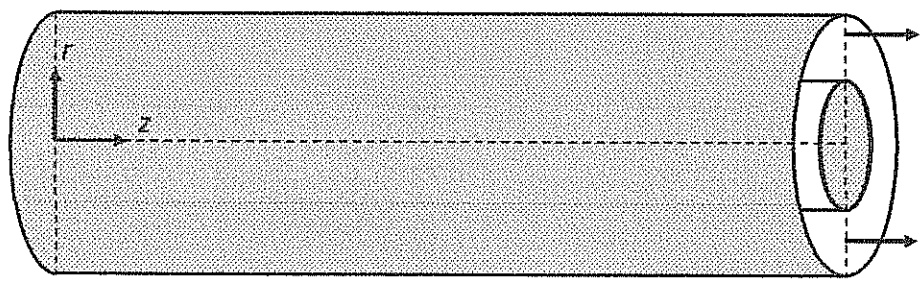
Name: SOLUTION  
Box #: \_\_\_\_\_

## Mini-Exam II

CM 3110 8 October 2009

Note:  
Significant figures count.  
Please box your final answers.  
Please be neat.

1. (50 points) For the apparatus shown in the figure below, an incompressible, Newtonian fluid is made to flow under an axial pressure gradient in the gap between two concentric cylinders. The flow is steady, and the inlet pressure is  $P_0$  and the outlet pressure is  $P_L$ . The tube is of length  $L$  and is horizontal. You may neglect gravity. The microscopic mass balance (continuity equation) and the microscopic momentum balance (Navier-Stokes equations) are shown on the next page. For each term in all four equations, cross out the terms that are zero and give a reason for each decision.



Side view:  
steady flow in  
annulus between  
cylinders

*see next page*

$$\frac{\partial p}{\partial t} + \frac{1}{r} \frac{\partial(p r v_r)}{\partial r} + \frac{1}{r} \frac{\partial(p v_\theta)}{\partial \theta} + \frac{\partial(p v_z)}{\partial z} = 0$$

$\frac{\partial p}{\partial t} \rightarrow$  steady  
 $\frac{1}{r} \frac{\partial(p r v_r)}{\partial r} \rightarrow v_r = 0$   
 $\frac{1}{r} \frac{\partial(p v_\theta)}{\partial \theta} \rightarrow v_\theta = 0$

$$\Rightarrow \boxed{\frac{\partial v_z}{\partial z} = 0}$$

$$\rho \left( \frac{\partial v_r}{\partial t} + v_r \frac{\partial v_r}{\partial r} + \frac{\partial v_r}{\partial r} + \frac{v_\theta \partial v_r}{r \partial \theta} - \frac{v_\theta^2}{r} + v_z \frac{\partial v_r}{\partial z} \right) = -\frac{\partial P}{\partial r} + \mu \left( \frac{\partial}{\partial r} \left( \frac{1}{r} \frac{\partial(r v_r)}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 v_r}{\partial \theta^2} + \frac{2}{r^2} \frac{\partial v_\theta}{\partial \theta} \right) + \rho g_r$$

$\frac{\partial v_r}{\partial t} \rightarrow$  steady state  
 $v_r \frac{\partial v_r}{\partial r} \rightarrow v_r = 0$   
 $\frac{\partial v_r}{\partial r} \rightarrow v_r = 0$   
 $\frac{v_\theta \partial v_r}{r \partial \theta} \rightarrow v_\theta = 0$   
 $-\frac{v_\theta^2}{r} \rightarrow v_\theta = 0$   
 $v_z \frac{\partial v_r}{\partial z} \rightarrow v_r = 0$   
 $-\frac{\partial P}{\partial r} \rightarrow v_r = 0$   
 $\frac{\partial}{\partial r} \left( \frac{1}{r} \frac{\partial(r v_r)}{\partial r} \right) \rightarrow v_r = 0$   
 $\frac{1}{r^2} \frac{\partial^2 v_r}{\partial \theta^2} \rightarrow v_r = 0$   
 $\frac{2}{r^2} \frac{\partial v_\theta}{\partial \theta} \rightarrow v_\theta = 0$   
 $\rho g_r \rightarrow$  neglect

$$\rho \left( \frac{\partial v_\theta}{\partial t} + v_r \frac{\partial v_\theta}{\partial r} + \frac{\partial v_\theta}{\partial r} + \frac{v_\theta \partial v_\theta}{r \partial \theta} + \frac{v_z \partial v_\theta}{\partial z} \right) = -\frac{1}{r} \frac{\partial P}{\partial \theta} + \mu \left( \frac{\partial}{\partial r} \left( \frac{1}{r} \frac{\partial(r v_\theta)}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 v_\theta}{\partial \theta^2} + \frac{2}{r^2} \frac{\partial v_r}{\partial \theta} \right) + \rho g_\theta$$

$\frac{\partial v_\theta}{\partial t} \rightarrow$  steady state  
 $v_r \frac{\partial v_\theta}{\partial r} \rightarrow v_\theta = 0$   
 $\frac{\partial v_\theta}{\partial r} \rightarrow v_\theta = 0$   
 $\frac{v_\theta \partial v_\theta}{r \partial \theta} \rightarrow v_\theta = 0$   
 $v_z \frac{\partial v_\theta}{\partial z} \rightarrow v_\theta = 0$   
 $-\frac{1}{r} \frac{\partial P}{\partial \theta} \rightarrow v_\theta = 0$   
 $\frac{\partial}{\partial r} \left( \frac{1}{r} \frac{\partial(r v_\theta)}{\partial r} \right) \rightarrow v_\theta = 0$   
 $\frac{1}{r^2} \frac{\partial^2 v_\theta}{\partial \theta^2} \rightarrow v_\theta = 0$   
 $\frac{2}{r^2} \frac{\partial v_r}{\partial \theta} \rightarrow v_r = 0$   
 $\rho g_\theta \rightarrow$  neglect

$$\rho \left( \frac{\partial v_z}{\partial t} + v_r \frac{\partial v_z}{\partial r} + \frac{\partial v_z}{\partial r} + \frac{v_\theta \partial v_z}{r \partial \theta} + \frac{\partial v_z}{\partial z} \right) = -\frac{\partial P}{\partial z} + \mu \left( \frac{1}{r} \frac{\partial}{\partial r} \left( r \frac{\partial v_z}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 v_z}{\partial \theta^2} \right) + \rho g_z$$

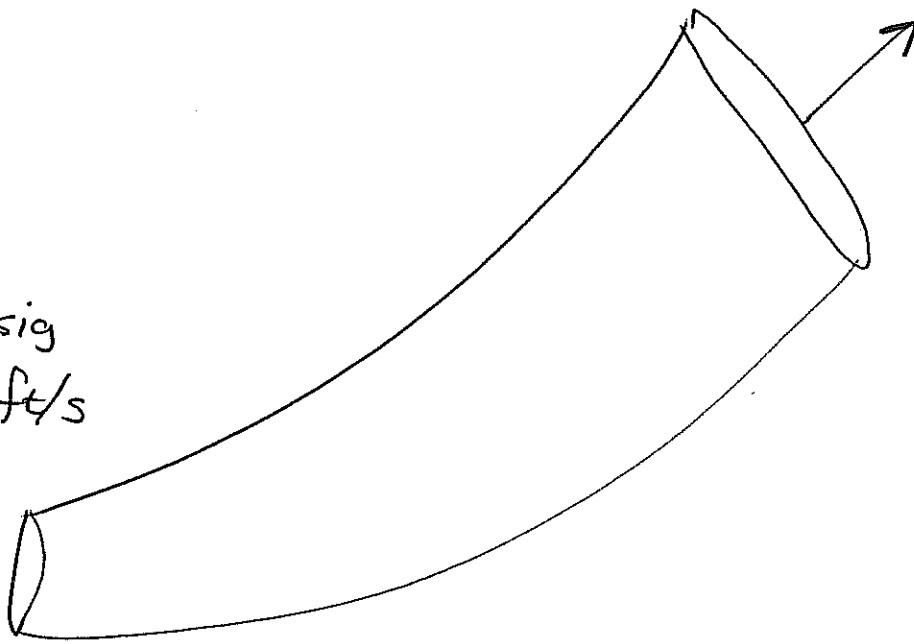
$\frac{\partial v_z}{\partial t} \rightarrow$  steady state  
 $v_r \frac{\partial v_z}{\partial r} \rightarrow v_r = 0$   
 $\frac{\partial v_z}{\partial r} \rightarrow v_r = 0$   
 $\frac{v_\theta \partial v_z}{r \partial \theta} \rightarrow v_\theta = 0$   
 $\frac{\partial v_z}{\partial z} \rightarrow$  continuity  
 $-\frac{\partial P}{\partial z} \rightarrow$  continuity  
 $\frac{1}{r} \frac{\partial}{\partial r} \left( r \frac{\partial v_z}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 v_z}{\partial \theta^2} \rightarrow$  continuity  
 $\rho g_z \rightarrow$  no z component to g  
 $\theta$ -Symmetry

2.

$$P_1 = 14.5 \text{ psig}$$

$$\langle V \rangle_1 = 12.23 \text{ ft/s}$$

$$z_1 = 0$$



$$P_2 = ?$$

$$\langle V \rangle_2 = 3.61 \frac{\text{ft}}{\text{s}}$$

$$z_2 = 0.5 \text{ ft}$$

Mechanical energy balance:

$$\frac{\Delta P}{\rho} + \frac{\Delta V^2}{2\alpha} + g\Delta z + \cancel{F} = \cancel{\frac{-W_s, \text{ by}}{m}}$$

$\alpha = 1$

fold to neglect      no work

$$\frac{P_2 - P_1}{\rho} + \frac{\langle V \rangle_2^2 - \langle V \rangle_1^2}{2} + g(z_2 - z_1) = 0$$

$$P_2 = \rho \left[ (z_1 - z_2)g + \frac{\langle V \rangle_1^2 - \langle V \rangle_2^2}{2} \right] + P_1$$

$$P_2 = \left( \frac{62.25 \text{ lb}_m}{\text{ft}^3} \right) \left[ - (0.5 \text{ ft}) \left( \frac{32.174 \text{ ft}}{\text{s}^2} \right) + \left[ \underbrace{\left( \frac{12.23 \text{ ft}}{\text{s}} \right)^2}_{149.5729} - \underbrace{\left( \frac{3.61 \text{ ft}}{\text{s}} \right)^2}_{13.0321} \right] \frac{1}{2} \right] + 14.5 \text{ psi}$$

$$P_2 = \left( \frac{62.25 \text{ lb}_m}{\text{ft}^3} \right) \left[ -16.087 \frac{\text{ft}^2}{\text{s}^2} + 68.2704 \frac{\text{ft}^2}{\text{s}^2} \right] + 14.5 \frac{\text{lb}_f}{\text{in}^2}$$

$$= \underbrace{3248.8524 \frac{\text{lb}_m}{\text{ft}^3} \frac{\text{s}^2 \text{ lb}_f}{32.174 \text{ ft} \text{ lb}_m} \frac{\text{ft}^2}{(12 \text{ in})^2}}_{0.70113} + 14.5 \frac{\text{lb}_f}{\text{in}^2}$$

$$P_2 = 15.2 \text{ psi}$$