

# Exam 1

①

CM4650

14 FEB 08

1. Connection:  $\underline{v} \cdot \nabla \underline{v}$

2.  $\underline{a} \cdot \nabla \underline{b} = a_i \hat{e}_i \cdot \frac{\partial b_j}{\partial x_p} \hat{e}_p \hat{e}_j$

$\delta_{ip}$   
"i becomes p"

$= a_p \frac{\partial b_j}{\partial x_p} \hat{e}_j$

3.  $u_k A_{jk} \frac{\partial w_p}{\partial x_j} \hat{e}_p$

$= \sum_{k=1}^3 \sum_{j=1}^3 \sum_{p=1}^3 u_k A_{jk} \frac{\partial w_p}{\partial x_j} \hat{e}_p$

2

$$4. \underline{\underline{A}} = \underline{\nabla V} + (\underline{\nabla V})^T$$

$$\underline{\nabla V} = \frac{\partial V_m}{\partial x_p} \hat{e}_p \hat{e}_m$$

to add, put on  
common index:  
1st = i second = j

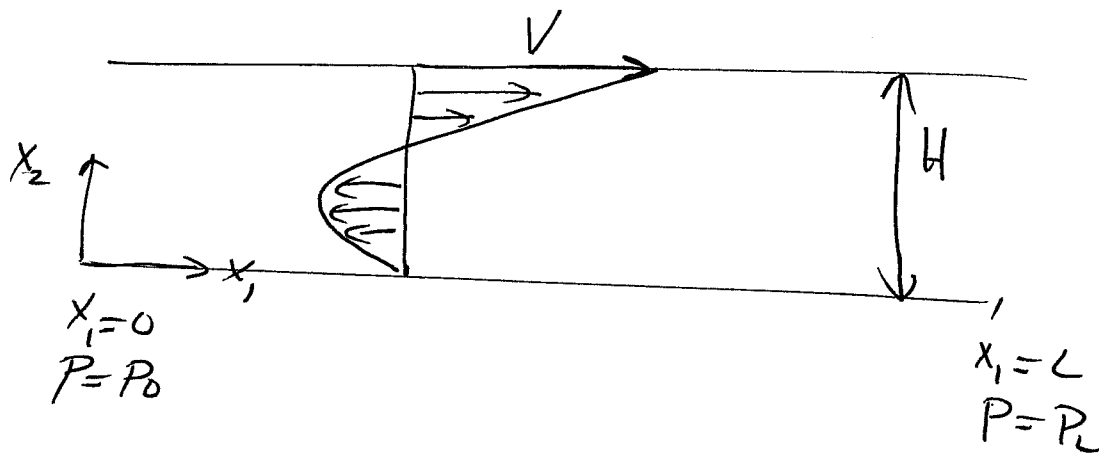
$$(\underline{\nabla V})^T = \frac{\partial V_m}{\partial x_p} \hat{e}_m \hat{e}_p$$

$$\underline{\nabla V} + (\underline{\nabla V})^T = \frac{\partial V_j}{\partial x_i} \hat{e}_i \hat{e}_j + \frac{\partial V_i}{\partial x_j} \hat{e}_i \hat{e}_j$$

$$= \left( \frac{\partial V_j}{\partial x_i} + \frac{\partial V_i}{\partial x_j} \right) \hat{e}_i \hat{e}_j$$

21-component  $\Rightarrow$   $i = 2$   
 $j = 1$

$$[\underline{\underline{A}}]_{21} = \left( \frac{\partial V_1}{\partial x_2} + \frac{\partial V_2}{\partial x_1} \right)$$



$$\rho \left( \underbrace{\frac{\partial \underline{v}}{\partial t}}_{\text{steady state}} + \underbrace{(\underline{v} \cdot \nabla) \underline{v}}_{\text{unidirectional flow}} \right) = -\nabla P + \mu \nabla^2 \underline{v} + \underbrace{\rho \underline{g}}_{\text{neglect}}$$

$$\nabla \cdot \underline{v} = 0 \quad \underline{v} = \begin{pmatrix} v_1 \\ 0 \\ 0 \end{pmatrix}_{123}$$

$$0 = \frac{\partial}{\partial x_i} e_i \cdot \overbrace{v_p \hat{e}_p}^{\delta_{ip} \text{ "i becomes p"}}$$

$$= \frac{\partial v_p}{\partial x_p} = \sum_{p=1}^3 \frac{\partial v_p}{\partial x_p} = \frac{\partial v_1}{\partial x_1} + \cancel{\frac{\partial v_2}{\partial x_2}} + \cancel{\frac{\partial v_3}{\partial x_3}}$$

$v_2 = 0$   
 $v_3 = 0$

$$\Rightarrow \boxed{\frac{\partial v_1}{\partial x_1} = 0}$$

(4)

$$\nabla^2 \underline{V} = \nabla \cdot \nabla \underline{V} = \frac{\partial}{\partial x_p} \hat{e}_p \cdot \frac{\partial}{\partial x_m} \hat{e}_m V_s \hat{e}_s$$

$\delta_{pm}$  "p becomes m"

$$= \frac{\partial}{\partial x_m} \frac{\partial}{\partial x_m} V_s \hat{e}_s$$

$$0 = \nabla \cdot \underline{V}$$

$$\nabla^2 \underline{V} = \left( \begin{array}{ccc} \cancel{\frac{\partial^2 V_1}{\partial x_1^2}} + \frac{\partial^2 V_1}{\partial x_2^2} + \frac{\partial^2 V_1}{\partial x_3^2} & & \\ \frac{\partial^2 V_2}{\partial x_1^2} + \cancel{\frac{\partial^2 V_2}{\partial x_2^2}} + \frac{\partial^2 V_2}{\partial x_3^2} & & \\ \frac{\partial^2 V_3}{\partial x_1^2} + \frac{\partial^2 V_3}{\partial x_2^2} + \cancel{\frac{\partial^2 V_3}{\partial x_3^2}} & & \end{array} \right)_{123}$$

$V_2 = 0$   
 $V_3 = 0$

$$\nabla^2 \underline{V} = \left( \begin{array}{c} \frac{\partial^2 V_1}{\partial x_2^2} \\ 0 \\ 0 \end{array} \right)_{123}$$

EQUATION OF MOTION:

(5)

$$0 = -\nabla P + \mu \nabla^2 \underline{V}$$

$$\begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}_{123} = \begin{pmatrix} -\frac{\partial P}{\partial x_1} \\ -\frac{\partial P}{\partial x_2} \\ -\frac{\partial P}{\partial x_3} \end{pmatrix}_{123} + \mu \begin{pmatrix} \frac{\partial^2 V_1}{\partial x_2^2} \\ 0 \\ 0 \end{pmatrix}_{123}$$

2-component:

$$\frac{\partial P}{\partial x_2} = 0$$

3-component:

$$\frac{\partial P}{\partial x_3} = 0$$

$\Rightarrow P = P(x_1)$   
only

1-component:

$$\frac{\partial P}{\partial x_1} = \mu \frac{\partial^2 V_1}{\partial x_2^2} \quad \textcircled{a}$$

note:  $V_1 = V_1(x_2)$  only due to continuity ( $\nabla \cdot \underline{V} = 0$ ) and wide plate assumption

6

$$\underbrace{\frac{dP}{dx_1}}_{f(x_1)} = \mu \underbrace{\frac{d^2V_1}{dx_2^2}}_{g(x_2)} = \lambda \Rightarrow \text{equal to same constant.}$$

$$\frac{dP}{dx_1} = \lambda$$

$$P = \lambda x_1 + C_1$$

2a)  $P = P_0 \quad x_1 = 0$   
 $P = P_L \quad x_1 = L$

3)  $P = \left( \frac{P_L - P_0}{L} \right) x_1 + P_0 \quad \lambda = \left( \frac{P_L - P_0}{L} \right)$

$$\mu \frac{d^2V_1}{dx_2^2} = \lambda$$

$$\frac{dV_1}{dx_2} = \frac{\lambda}{\mu} x_2 + C_2$$

$$V_1 = \frac{\lambda x_2^2}{2\mu} + C_2 x_2 + C_3$$

②⑥ B.C.  $X=0 \quad V_1=0 \Rightarrow C_3=0$   
 $X=H \quad V_1=V$

⑦

$$V = \frac{\lambda H^2}{2\mu} + C_2 H$$

$$C_2 = \frac{V}{H} - \frac{\lambda H^2}{2\mu H}$$

$$C_2 = \frac{V}{H} - \frac{\lambda H}{2\mu}$$

$$V_1 = \frac{\lambda}{2\mu} X_2^2 + \frac{V}{H} X_2 - \frac{\lambda H}{2\mu} X_2$$

$$= \frac{\lambda}{2\mu} (X_2^2 - H X_2) + \frac{V}{H} X_2$$

$$= \frac{\lambda H^2}{2\mu} \left( \left(\frac{X_2}{H}\right)^2 - \left(\frac{X_2}{H}\right) \right) + V \left(\frac{X_2}{H}\right)$$

⑧

$$V_1 = \left( \frac{P_2 - P_0}{2L\mu} \right) H^2 \left( \left(\frac{X_2}{H}\right)^2 - \left(\frac{X_2}{H}\right) \right) + V \left(\frac{X_2}{H}\right)$$

6. bonus

$$u_k A_{jk} \frac{\partial W_p}{\partial x_j} e_p$$

but  $k+j$  dim + match; must be  $A^T$

try  $\underline{u} \cdot \underline{A}^T \cdot \underline{\nabla} W =$

$$u_i \hat{e}_i \cdot A_{ik} \hat{e}_k \hat{e}_p \cdot \frac{\partial W_m}{\partial x_s} \hat{e}_s \hat{e}_m$$

$\delta_{ik}$  "i becomes k"

$\delta_{bs}$  "b becomes s"

$$u_k A_{sk} \frac{\partial W_m}{\partial x_s} \hat{e}_m \quad \checkmark \text{ correct}$$

$$\underline{u} \cdot \underline{A}^T \cdot \underline{\nabla} W$$